

Large deviations for locally monotone stochastic partial differential equations driven by Lévy noise

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We establish a large deviation principle for a type of stochastic partial differential equations (SPDEs) with locally monotone coefficients driven by Lévy noise. The weak convergence method plays an important role.

Keywords: Freidlin-Wentzell type large deviation principle, locally monotone coefficients, stochastic partial differential equations, Levy Processes.

1. Introduction

We shall prove via the weak convergence approach developed by [Budhiraja, A., Chen, J. and Dupuis, P. \(2013\)](#); [Budhiraja, A., Dupuis, P. and Maroulas, V. \(2011\)](#); [Dupuis, P. and Ellis, R. \(1997\)](#) the Freidlin-Wentzell type large deviation principle (LDP) for a family of locally monotone stochastic partial differential equations (SPDEs) driven by Lévy processes, these SPDEs include stochastic reaction-diffusion equations, stochastic Burgers type equations, stochastic 2D Navier-Stokes equations and stochastic equations of non-Newtonian fluids.

Let V be a reflexive and separable Banach space, which is densely and continuously injected in a separable Hilbert space $(H, \langle \cdot, \cdot \rangle_H)$. Identifying H with its dual we get

$$V \subset H \cong H^* \subset V^*,$$

where the star “*” denotes the dual spaces. Denote $\langle \cdot, \cdot \rangle_{V^*, V}$ the duality between V^* and V , then we have

$$\langle u, v \rangle_{V^*, V} = \langle u, v \rangle_H, \quad \forall u \in H, v \in V.$$

Fix $T > 0$ and let $(\Omega, \mathcal{F}, (\mathcal{F}_t)_{t \in [0, T]}, \mathbb{P})$ be a complete separable filtration probability space. Let \mathcal{P} be the predictable σ -field, that is the σ -field on $[0, T] \times \Omega$ generated by all

left continuous and \mathcal{F}_t -adapted real-valued processes. Further denote by \mathcal{BF} the σ -field of the progressively measurable sets on $[0, T] \times \Omega$, i.e.

$$\mathcal{BF} = \{O \subset [0, T] \times \Omega : \forall t \in [0, T], O \cap ([0, t] \times \Omega) \in \mathcal{B}([0, t]) \otimes \mathcal{F}_t\},$$

where $\mathcal{B}([0, t])$ denotes the Borel σ -field on $[0, t]$.

Now we consider the following type of SPDEs driven by Lévy processes:

$$\begin{aligned} dX_t^\epsilon &= \mathcal{A}(t, X_t^\epsilon)dt + \epsilon \int_{\mathbb{X}} f(t, X_{t-}^\epsilon, z) \tilde{N}^{\epsilon^{-1}}(dt, dz), \\ X_0^\epsilon &= x \in H, \end{aligned} \quad (1.1)$$

where $\mathcal{A} : [0, T] \times V \rightarrow V^*$ is a $\mathcal{B}([0, T]) \otimes \mathcal{B}(V)$ -measurable function. \mathbb{X} is a locally compact Polish space. $N^{\epsilon^{-1}}$ is a Poisson random measure on $[0, T] \times \mathbb{X}$ with a σ -finite mean measure $\epsilon^{-1} \lambda_T \otimes \nu$, λ_T is the Lebesgue measure on $[0, T]$ and ν is a σ -finite measure on \mathbb{X} .

$$\tilde{N}^{\epsilon^{-1}}([0, t] \times B) = N^{\epsilon^{-1}}([0, t] \times B) - \epsilon^{-1} t \nu(B), \quad \forall B \in \mathcal{B}(\mathbb{X}) \text{ with } \nu(B) < \infty,$$

is the compensated Poisson random measure. $f : [0, T] \times V \times \mathbb{X} \rightarrow H$ is a $\mathcal{B}([0, T]) \otimes \mathcal{B}(V) \otimes \mathcal{B}(\mathbb{X})$ -measurable function.

The following assumptions are from [Brzeźniak, Z., Liu, W. and Zhu, J. \(2014\)](#), which guarantee that Eq. (1.1) admits a unique solution. Suppose that there exist constants $\alpha > 1$, $\beta \geq 0$, $\theta > 0$, $C > 0$, positive functions K and F and a function $\rho : V \rightarrow [0, +\infty)$ which is measurable and bounded on the balls, such that the following conditions hold for all $v, v_1, v_2 \in V$ and $t \in [0, T]$:

(H1) (Hemicontinuity) The map $s \mapsto \langle \mathcal{A}(t, v_1 + sv_2), v \rangle_{V^*, V}$ is continuous on \mathbb{R} .

(H2) (Local monotonicity)

$$\begin{aligned} & 2\langle \mathcal{A}(t, v_1) - \mathcal{A}(t, v_2), v_1 - v_2 \rangle_{V^*, V} + \int_{\mathbb{X}} \|f(t, v_1, z) - f(t, v_2, z)\|_H^2 \nu(dz) \\ & \leq (K_t + \rho(v_2)) \|v_1 - v_2\|_H^2, \end{aligned}$$

(H3) (Coercivity)

$$2\langle \mathcal{A}(t, v), v \rangle_{V^*, V} + \theta \|v\|_V^\alpha \leq F_t(1 + \|v\|_H^2).$$

(H4) (Growth)

$$\|\mathcal{A}(t, v)\|_{V^*}^{\frac{\alpha}{\alpha-1}} \leq (F_t + C\|v\|_V^\alpha)(1 + \|v\|_H^\beta).$$

Definition 1.1. An H -valued càdlàg \mathcal{F}_t -adapted process $\{X_t^\epsilon\}_{t \in [0, T]}$ is called a solution of Eq. (1.1), if for its $dt \times \mathbb{P}$ -equivalent class \widehat{X}^ϵ we have

- (1) $\widehat{X}^\epsilon \in L^\alpha([0, T]; V) \cap L^2([0, T]; H)$, \mathbb{P} -a.s.;
- (2) the following equality holds \mathbb{P} -a.s.:

$$X_t^\epsilon = x + \int_0^t \mathcal{A}(s, \overline{X}_s^\epsilon) ds + \epsilon \int_0^t \int_{\mathbb{X}} f(s, \overline{X}_s^\epsilon, z) \tilde{N}^{\epsilon^{-1}}(ds, dz), \quad t \in [0, T],$$

where \overline{X}^ϵ is any V -valued progressively measurable $dt \times \mathbb{P}$ version of \widehat{X}^ϵ .

Remark 1.1. It is a well-known and typical conclusion in probability theory that $dt \times \mathbb{P}$ -equivalent processes/versions are regarded as the same stochastic process, and it is always impossible to find one version to satisfy all required properties. In the above definition, three $dt \times \mathbb{P}$ -equivalent versions “ X^ϵ , \widehat{X}^ϵ , \overline{X}^ϵ ” are implicitly required to ensure that each version satisfies some required properties.

With a minor modification of (Brzeźniak, Z., Liu, W. and Zhu, J., 2014, Theorem 1.2), we have the following existence and uniqueness theorem for the solution of Eq. (1.1).

Theorem 1.1. *Suppose that conditions (H1)-(H4) hold for $F, K \in L^1([0, T]; \mathbb{R}^+)$, and there exists a constant $\gamma < \frac{\theta}{2\beta}$ and $G \in L^1([0, T]; \mathbb{R}^+)$ such that for all $t \in [0, T]$ and $v \in V$ we have*

$$\int_{\mathbb{X}} \|f(t, v, z)\|_H^2 \nu(dz) \leq F_t(1 + \|v\|_H^2) + \gamma \|v\|_V^\theta; \quad (1.2)$$

$$\int_{\mathbb{X}} \|f(t, v, z)\|_H^{\beta+2} \nu(dz) \leq G_t(1 + \|v\|_H^{\beta+2}); \quad (1.3)$$

$$\rho(v) \leq C(1 + \|v\|_V^\theta)(1 + \|v\|_H^\beta). \quad (1.4)$$

Then

- (1) For any $x \in L^{\beta+2}(\Omega, \mathcal{F}_0, \mathbb{P}; H)$, (1.1) has a unique solution $\{X_t^\epsilon\}_{t \in [0, T]}$.
- (2) If γ is small enough, then

$$\mathbb{E} \left(\sup_{t \in [0, T]} \|X_t^\epsilon\|_H^{\beta+2} \right) + \mathbb{E} \int_0^T \|X_t^\epsilon\|_H^\beta \|X_t^\epsilon\|_V^\alpha dt \leq C_\epsilon \left(\mathbb{E} \|x\|_H^{\beta+2} + \int_0^T G_t dt + \int_0^T F_t dt \right).$$

Remark 1.2. The assumptions in Theorem 1.1 are satisfied by a very large class of SPDEs driven by a multiplicative pure jump Lévy noise, including the stochastic porous medium equation, stochastic p-Laplace equation, stochastic Burgers type equations, stochastic 2D Navier-Stokes equations and many other stochastic hydrodynamical systems. Section 2 in Brzeźniak, Z., Liu, W. and Zhu, J. (2014) presents many concrete examples to illustrate the applications of this theorem. It is omitted in this paper.

Our aim in the present paper is to establish a LDP for the solution of (1.1) as $\epsilon \rightarrow 0$ on $D([0, T], H)$, the space of H -valued càdlàg functions on $[0, T]$.

In the past three decades, there are numerous literatures about the LDP for stochastic evolution equations (SEEs) and SPDEs driven by Gaussian processes (cf. Bessaih, H. and Millet, A. (2009); Budhiraja, A. and Dupuis, P. (2000); Budhiraja, A., Dupuis, P. and

Maroulas, V. (2008); Cardon-Weber, C. (1999); Cerrai, S. and Röckner, M. (2004); Chenal, F. and Millet, A. (1997); Chow, P. (1992); Duan, J. and Millet, A. (2009); Kallianpur, G. and Xiong, J. (1996); Manna, U. Sritharan, S.S. and Sundar, P. (2009); Liu, W. (2010); Ren, J. and Zhang, X. (2008); Röckner, M., Zhang, T. and Zhang, X. (2010); Sowers, R.B. (1992); Zhang, T. (2002); Zhang, X. (2010), etc.). Many of these results were obtained by using the weak convergence approach for the case of Gaussian noise, introduced by Budhiraja, A. and Dupuis, P. (2000); Budhiraja, A., Dupuis, P. and Maroulas, V. (2008), see, for example, Bessaih, H. and Millet, A. (2009); Budhiraja, A. and Dupuis, P. (2000); Budhiraja, A., Dupuis, P. and Maroulas, V. (2008); Duan, J. and Millet, A. (2009); Manna, U. Sritharan, S.S. and Sundar, P. (2009); Liu, W. (2010); Ren, J. and Zhang, X. (2008); Röckner, M., Zhang, T. and Zhang, X. (2010); Zhang, X. (2010). This approach has been proved to be very effective for various finite/infinite-dimensional stochastic dynamical systems. One of the main advantages of this approach is that one only needs to make some necessary moment estimates.

The situations for SEEs and SPDEs driven by Lévy noise are drastically different because of the appearance of the jumps. There are only a few results on this topic so far. The first paper on LDP for SEEs of jump type is Röckner, M. and Zhang, T. (2007) where the additive noise is considered. The study of LDP for multiplicative Lévy noise has been carried out as well, e.g., Swiech, A. and Zabczyk, J. (2011) and Budhiraja, A., Chen, J. and Dupuis, P. (2013) for SEEs where the LDP was established on a space larger (hence, with a weaker topology) than the actual state space of the solution, Yang, X., Zhai, J. and Zhang, T. (2015) for SEEs on the actual state space, Zhai, J. and Zhang, T. (2015) for the 2-D stochastic Navier-Stokes equations (SNSEs). Before Zhai, J. and Zhang, T. (2015), Xu, T. and Zhang, T. (2009) dealt with the 2-D SNSEs driven by additive Lévy noise. We also refer to de Acosta, A. (2000, 1994); Bao, J. and Yuan, C. (2015); Feng, J. and Kurtz, T. (2006) for related results.

To obtain our result, we will use the weak convergence approach introduced by Budhiraja, A., Chen, J. and Dupuis, P. (2013); Budhiraja, A., Dupuis, P. and Maroulas, V. (2011) for the case of Poisson random measures. This approach is a powerful tool to prove the LDP for SEEs and SPDEs driven by Lévy noise, which has been applied for several dynamical systems. The weak convergence method was first used in Budhiraja, A., Chen, J. and Dupuis, P. (2013) to obtain LDP for SPDEs on co-nuclear spaces driven by Lévy noises, and then in Yang, X., Zhai, J. and Zhang, T. (2015) for SPDEs on Hilbert spaces with regular coefficients. Paper Zhai, J. and Zhang, T. (2015) deals with the 2-D SNSEs driven by multiplicative Lévy noise. Bao and Yuan Bao, J. and Yuan, C. (2015) established a LDP for a class of stochastic functional differential equations of neutral type driven by a finite-dimensional Wiener process and a stationary Poisson random measure.

Monotone method is a main tool to prove the existence and uniqueness of SPDEs, and it can tackle a large class of SPDEs, for more details, see Brzeźniak, Z., Liu, W. and Zhu, J. (2014); Liu, W. and Röckner, M. (2010) and references therein. Working in the framework of Brzeźniak, Z., Liu, W. and Zhu, J. (2014), the purpose of this paper is to establish a LDP for a family of locally monotone SPDEs (1.1) driven by pure jumps. In addition to the difficulties caused by the jumps, much of our problem is to deal with the monotone operator \mathcal{A} .

This paper is organized as follows. In Section 2, we will recall the abstract criteria for LDP obtained in [Budhiraja, A., Dupuis, P. and Maroulas, V. \(2011\)](#). In Section 3, we will show the main result of this paper. Section 4 and Section 5 is devoted to prove prior results on the controlled SPDEs (4.4), which play a key role in this paper. The entire Section 6 is to establish the LDP for (1.1).

2. Preliminaries

2.1. Poisson Random Measure

For convenience of the reader, we shall adopt the notation in [Budhiraja, A., Chen, J. and Dupuis, P. \(2013\)](#) and [Budhiraja, A., Dupuis, P. and Maroulas, V. \(2011\)](#). Recall that \mathbb{X} is a locally compact Polish space. Denote by $\mathcal{M}_{FC}(\mathbb{X})$ the collection of all measures on $(\mathbb{X}, \mathcal{B}(\mathbb{X}))$ such that $\nu(K) < \infty$ for any compact $K \in \mathcal{B}(\mathbb{X})$. Denote by $C_c(\mathbb{X})$ the space of continuous functions with compact supports, endow $\mathcal{M}_{FC}(\mathbb{X})$ with the weakest topology such that for every $f \in C_c(\mathbb{X})$, the function

$$\nu \rightarrow \langle f, \nu \rangle = \int_{\mathbb{X}} f(u) d\nu(u),$$

is continuous for $\nu \in \mathcal{M}_{FC}(\mathbb{X})$. This topology can be metrized such that $\mathcal{M}_{FC}(\mathbb{X})$ is a Polish space (see e.g. [Budhiraja, A., Dupuis, P. and Maroulas, V. \(2011\)](#)).

Fixing $T \in (0, \infty)$, we denote $\mathbb{X}_T = [0, T] \times \mathbb{X}$ and $\nu_T = \lambda_T \otimes \nu$ with λ_T being Lebesgue measure on $[0, T]$ and $\nu \in \mathcal{M}_{FC}(\mathbb{X})$. Let \mathbf{n} be a Poisson random measure on \mathbb{X}_T with intensity measure ν_T , it is well-known [Ikeda, N. and Watanabe, S. \(1981\)](#) that \mathbf{n} is an $\mathcal{M}_{FC}(\mathbb{X}_T)$ valued random variable such that

- (i) for each $B \in \mathcal{B}(\mathbb{X}_T)$ with $\nu_T(B) < \infty$, $\mathbf{n}(B)$ is Poisson distributed with mean $\nu_T(B)$;
- (ii) for disjoint $B_1, \dots, B_k \in \mathcal{B}(\mathbb{X}_T)$, $\mathbf{n}(B_1), \dots, \mathbf{n}(B_k)$ are mutually independent random variables.

For notational simplicity, we write from now on

$$\mathbb{M} = \mathcal{M}_{FC}(\mathbb{X}_T), \tag{2.1}$$

and denote by \mathbb{P} the probability measure induced by \mathbf{n} on $(\mathbb{M}, \mathcal{B}(\mathbb{M}))$. Under \mathbb{P} , the canonical map, $N : \mathbb{M} \rightarrow \mathbb{M}$, $N(m) \doteq m$, is a Poisson random measure with intensity measure ν_T . With applications to large deviations in mind, we also consider, for $\theta > 0$, probability measures \mathbb{P}_θ on $(\mathbb{M}, \mathcal{B}(\mathbb{M}))$ under which N is a Poisson random measure with intensity $\theta\nu_T$. The corresponding expectation operators will be denoted by \mathbb{E} and \mathbb{E}_θ , respectively.

For further use, simply denote

$$\mathbb{Y} = \mathbb{X} \times [0, \infty), \quad \mathbb{Y}_T = [0, T] \times \mathbb{Y}, \quad \bar{\mathbb{M}} = \mathcal{M}_{FC}(\mathbb{Y}_T). \tag{2.2}$$

Let $\bar{\mathbb{P}}$ be the unique probability measure on $(\bar{\mathbb{M}}, \mathcal{B}(\bar{\mathbb{M}}))$ under which the canonical map, $\bar{N} : \bar{\mathbb{M}} \rightarrow \bar{\mathbb{M}}, \bar{N}(\bar{m}) \doteq \bar{m}$, is a Poisson random measure with intensity measure $\bar{\nu}_T = \lambda_T \otimes \nu \otimes \lambda_\infty$, with λ_∞ being Lebesgue measure on $[0, \infty)$. The corresponding expectation operator will be denoted by $\bar{\mathbb{E}}$. Let $\bar{\mathcal{F}}_t \doteq \sigma\{\bar{N}((0, s] \times A) : 0 \leq s \leq t, A \in \mathcal{B}(\bar{\mathbb{Y}})\}$, and let $\bar{\mathcal{F}}_t$ denote the completion under $\bar{\mathbb{P}}$. We denote by $\bar{\mathcal{P}}$ the predictable σ -field on $[0, T] \times \bar{\mathbb{M}}$ with the filtration $\{\bar{\mathcal{F}}_t : 0 \leq t \leq T\}$ on $(\bar{\mathbb{M}}, \mathcal{B}(\bar{\mathbb{M}}))$. Let $\bar{\mathbb{A}}$ be the class of all $(\bar{\mathcal{P}} \otimes \mathcal{B}(\bar{\mathbb{X}}))/\mathcal{B}([0, \infty))$ -measurable maps $\varphi : \bar{\mathbb{X}}_T \times \bar{\mathbb{M}} \rightarrow [0, \infty)$. For $\varphi \in \bar{\mathbb{A}}$, we shall suppress the argument \bar{m} in $\varphi(s, x, \bar{m})$ and simply write $\varphi(s, x) = \varphi(s, x, \bar{m})$. Define a counting process N^φ on $\bar{\mathbb{X}}_T$ by

$$N^\varphi((0, t] \times U) = \int_{(0, t] \times U} \int_{(0, \infty)} 1_{[0, \varphi(s, x)]}(r) \bar{N}(ds dx dr), \quad t \in [0, T], U \in \mathcal{B}(\bar{\mathbb{X}}). \quad (2.3)$$

The above N^φ is called a controlled random measure, with φ selecting the intensity for the points at location x and time s , in a possibly random but non-anticipating way. When $\varphi(s, x, \bar{m}) \equiv \theta \in (0, \infty)$, we write $N^\varphi = N^\theta$. Note that N^θ has the same distribution with respect to $\bar{\mathbb{P}}$ as N has with respect to \mathbb{P}_θ . The following is a representation formula proved in [Budhiraja, A., Dupuis, P. and Maroulas, V. \(2011\)](#).

Theorem 2.1. *Let $F \in M_b(\bar{\mathbb{M}})$. Then, for $\theta > 0$,*

$$-\log \mathbb{E}_\theta(e^{-F(N)}) = -\log \bar{\mathbb{E}}(e^{-F(N^\theta)}) = \inf_{\varphi \in \bar{\mathbb{A}}} \bar{\mathbb{E}} \left[\theta L_T(\varphi) + F(N^{\theta\varphi}) \right].$$

2.2. A general criterion for large deviation principle ([Budhiraja, A., Chen, J. and Dupuis, P., 2013](#), Theorem 2.4)

We first state the large deviation principle we are concerned with. Let $\{X^\epsilon, \epsilon > 0\} \equiv \{X^\epsilon\}$ be a family of random variables defined on a probability space $(\Omega, \mathcal{F}, \mathbb{P})$ and taking values in a Polish space \mathcal{E} . Denote the expectation with respect to \mathbb{P} by \mathbb{E} . The theory of large deviations is concerned with events A for which probability $\mathbb{P}(X^\epsilon \in A)$ converges to zero exponentially fast as $\epsilon \rightarrow 0$. The exponential decay rate of such probabilities is typically expressed in terms of a 'rate function' I defined as below.

Definition 2.1. (Rate function) *A function $I : \mathcal{E} \rightarrow [0, \infty]$ is called a rate function on \mathcal{E} , if for each $M < \infty$ the level set $\{y \in \mathcal{E} : I(y) \leq M\}$ is a compact subset of \mathcal{E} . For $A \in \mathcal{B}(\mathcal{E})$, we define $I(A) \doteq \inf_{y \in A} I(y)$.*

Definition 2.2. (Large deviation principle) *Let I be a rate function on \mathcal{E} . The sequence $\{X^\epsilon\}$ is said to satisfy a large deviation principle (LDP) on \mathcal{E} with rate function I if the following two conditions hold.*

a. *LDP upper bound. For each closed subset F of \mathcal{E} ,*

$$\limsup_{\epsilon \rightarrow 0} \epsilon \log \mathbb{P}(X^\epsilon \in F) \leq -I(F).$$

b. *LDP lower bound.* For each open subset G of \mathcal{E} ,

$$\liminf_{\epsilon \rightarrow 0} \epsilon \log \mathbb{P}(X^\epsilon \in G) \geq -I(G).$$

Next, we recall the general criterion for large deviation principles established in [Budhiraja, A., Chen, J. and Dupuis, P. \(2013\)](#). Let $\{\mathcal{G}^\epsilon\}_{\epsilon > 0}$ be a family of measurable maps from \mathbb{M} to \mathbb{U} , where \mathbb{M} is introduced in (2.1) and \mathbb{U} is a Polish space. We present below a sufficient condition for LDP of the family $Z^\epsilon = \mathcal{G}^\epsilon(\epsilon N^{\epsilon^{-1}})$, as $\epsilon \rightarrow 0$.

Define

$$S^N = \left\{ g : \mathbb{X}_T \rightarrow [0, \infty) : L_T(g) \leq N \right\}, \quad (2.4)$$

a function $g \in S^N$ can be identified with a measure $\nu_T^g \in \mathbb{M}$, defined by

$$\nu_T^g(A) = \int_A g(s, x) \nu_T(ds dx), \quad A \in \mathcal{B}(\mathbb{X}_T).$$

This identification induces a topology on S^N under which S^N is a compact space, see the Appendix of [Budhiraja, A., Chen, J. and Dupuis, P. \(2013\)](#). Throughout this paper we use this topology on S^N . Denote $S = \cup_{N=1}^\infty S^N$ and $\bar{\mathbb{A}}^N := \{\varphi \in \bar{\mathbb{A}} \text{ and } \varphi(\omega) \in S^N, \bar{\mathbb{P}}\text{-a.s.}\}$.

Let $\{K_n \subset \mathbb{X}, n = 1, 2, \dots\}$ be an increasing sequence of compact sets such that $\cup_{n=1}^\infty K_n = \mathbb{X}$. For each n , let

$$\begin{aligned} \bar{\mathbb{A}}_{b,n} &= \left\{ \varphi \in \bar{\mathbb{A}} : \text{for all } (t, \omega) \in [0, T] \times \bar{\mathbb{M}}, n \geq \varphi(t, x, \omega) \geq 1/n \text{ if } x \in K_n \right. \\ &\quad \left. \text{and } \varphi(t, x, \omega) = 1 \text{ if } x \in K_n^c \right\}, \end{aligned}$$

and let $\bar{\mathbb{A}}_b = \cup_{n=1}^\infty \bar{\mathbb{A}}_{b,n}$. Define $\tilde{\mathbb{A}}^N = \bar{\mathbb{A}}^N \cap \{\phi : \phi \in \bar{\mathbb{A}}_b\}$.

Condition 2.1. *There exists a measurable map $\mathcal{G}^0 : \mathbb{M} \rightarrow \mathbb{U}$ such that the following hold.*

a). *For all $N \in \mathbb{N}$, let $g_n, g \in S^N$ be such that $g_n \rightarrow g$ as $n \rightarrow \infty$. Then*

$$\mathcal{G}^0(\nu_T^{g_n}) \rightarrow \mathcal{G}^0(\nu_T^g) \quad \text{in } \mathbb{U}.$$

b). *For all $N \in \mathbb{N}$, let $\varphi_\epsilon, \varphi \in \tilde{\mathbb{A}}^N$ be such that φ_ϵ converges in distribution to φ as $\epsilon \rightarrow 0$. Then*

$$\mathcal{G}^\epsilon(\epsilon N^{\epsilon^{-1}} \varphi_\epsilon) \Rightarrow \mathcal{G}^0(\nu_T^\varphi).$$

In this paper, we use the symbol “ \Rightarrow ” to denote convergence in distribution.

For $\phi \in \mathbb{U}$, define $\mathbb{S}_\phi = \left\{g \in S : \phi = \mathcal{G}^0\left(\nu_T^g\right)\right\}$. Let $I : \mathbb{U} \rightarrow [0, \infty]$ be defined by

$$I(\phi) = \inf_{g \in \mathbb{S}_\phi} L_T(g), \quad \phi \in \mathbb{U}. \quad (2.5)$$

By convention, $I(\phi) = \infty$ if $\mathbb{S}_\phi = \emptyset$.

The following criterion for LDP was established in Theorem 2.4 of [Budhiraja, A., Chen, J. and Dupuis, P. \(2013\)](#), which is a strengthened form of Theorem 4.2 of [Budhiraja, A., Dupuis, P. and Maroulas, V. \(2011\)](#), and for applications, it is more useful.

Theorem 2.2. *For $\epsilon > 0$, let Z^ϵ be defined by $Z^\epsilon = \mathcal{G}^\epsilon\left(\epsilon N^{\epsilon^{-1}}\right)$, and suppose that Condition 2.1 holds. Then the family $\{Z^\epsilon\}_{\epsilon > 0}$ satisfies a large deviation principle with the rate function I defined by (2.5).*

3. LDP for Eq. (1.1)

Assume that $X_0 = x \in H$ is deterministic. Let X^ϵ be the H -valued solution to Eq. (1.1) with initial value x . In this section, we state the LDP on $D([0, T], H)$ for $\{X^\epsilon\}$ under suitable assumptions.

Take $\mathbb{U} = D([0, T], H)$ in Condition 2.1 with the Skorokhod topology \mathbb{U}_S . We know that $(\mathbb{U}, \mathbb{U}_S)$ is a Polish space. For $p > 0$, define

$$\begin{aligned} \mathcal{H}_p &= \left\{h : [0, T] \times \mathbb{X} \rightarrow \mathbb{R}^+ : \exists \delta > 0, \text{ s.t. } \forall \Gamma \in \mathcal{B}([0, T]) \otimes \mathcal{B}(\mathbb{X}) \text{ with } \nu_T(\Gamma) < \infty, \right. \\ &\quad \left. \text{we have } \int_\Gamma \exp(\delta h^p(t, y)) \nu(dy) dt < \infty \right\}. \end{aligned}$$

Remark 3.1. It is easy to check that $\mathcal{H}_p \subset \mathcal{H}_{p'}$ for any $p' \in (0, p)$ and

$$\left\{h : [0, T] \times \mathbb{X} \rightarrow \mathbb{R}^+, \sup_{(t, y) \in [0, T] \times \mathbb{X}} h(t, y) < \infty\right\} \subset \mathcal{H}_p, \quad \forall p > 0.$$

To study LDP of Eq. (1.1), besides the assumptions (H1)-(H4), we further need

(H5) There exist $\eta_0 > 0$, $p \geq \Upsilon$ with $\Upsilon := \frac{2\beta(\alpha-1)(\alpha+\eta_0)}{\alpha} \vee \frac{4(\alpha-1)(\alpha+\eta_0)}{\alpha} \vee 4 \vee (\beta+2)$, and $L_f \in L_2(\nu_T) \cap L_4(\nu_T) \cap L_{\beta+2}(\nu_T) \cap L_\Upsilon(\nu_T) \cap L_{\frac{\Upsilon}{2}}(\nu_T) \cap \mathcal{H}_p$ such that

$$\|f(t, v, z)\|_H \leq L_f(t, z)(1 + \|v\|_H), \quad \forall (t, v, z) \in [0, T] \times V \times \mathbb{X}.$$

(H6) There exists $G_f \in L_2(\nu_T) \cap \mathcal{H}_2$ such that

$$\|f(t, v_1, z) - f(t, v_2, z)\|_H \leq G_f(t, z)\|v_1 - v_2\|_H, \quad \forall (t, z) \in [0, T] \times \mathbb{X}, \quad v_1, v_2 \in V.$$

Remark 3.2. It is easy to check that

$$\begin{aligned} & L_2(\nu_T) \cap \left\{ h : [0, T] \times \mathbb{X} \rightarrow \mathbb{R}^+, \|h\|_\infty < \infty \right\} \\ \subset & L_2(\nu_T) \cap L_4(\nu_T) \cap L_{\beta+2}(\nu_T) \cap L_{\Upsilon}(\nu_T) \cap L_{\frac{\Upsilon}{2}}(\nu_T) \cap \mathcal{H}_p, \end{aligned}$$

where $\|h\|_\infty = \sup_{(t,y) \in [0,T] \times \mathbb{X}} h(t,y)$.

It follows from Theorem 1.1 that, for every $\epsilon > 0$, there exists a measurable map $\mathcal{G}^\epsilon: \bar{\mathbb{M}} \rightarrow D([0, T]; H)$ such that, for any Poisson random measure $\mathbf{n}^{\epsilon^{-1}}$ on $[0, T] \times \mathbb{X}$ with mean measure $\epsilon^{-1} \lambda_T \otimes \nu$ given on some probability space, $\mathcal{G}^\epsilon(\epsilon \mathbf{n}^{\epsilon^{-1}})$ is the unique solution X^ϵ of (1.1) with $\tilde{N}^{\epsilon^{-1}}$ replaced by $\tilde{\mathbf{n}}^{\epsilon^{-1}}$, here $\tilde{\mathbf{n}}^{\epsilon^{-1}}$ is the compensated Poisson random measure of $\mathbf{n}^{\epsilon^{-1}}$.

To state our main result, we need to introduce the map \mathcal{G}^0 . Recall S given in Section 2.2. For $g \in S$, consider the following deterministic PDE (the skeleton equation):

$$X_t^{0,g} = x + \int_0^t \mathcal{A}(s, X_s^{0,g}) ds + \int_0^t f(s, X_s^{0,g}, z)(g(s, z) - 1) \nu(dz) ds, \quad \text{in } V^*.$$

By Proposition 5.1 below, this equation has a unique solution $X^{0,g} \in C([0, T], H) \cap L^\alpha([0, T], V)$. Define

$$\mathcal{G}^0(\nu_T^g) := X^{0,g}, \quad \forall g \in S. \quad (3.1)$$

Let $I: \mathbb{U} = D([0, T], H) \rightarrow [0, \infty]$ be defined as in (2.5). The following is the main result of this paper.

Theorem 3.1. *Assume that (H1)-(H6) and (1.4) hold. Then the family $\{X^\epsilon\}_{\epsilon > 0}$ satisfies an LDP on $D([0, T], H)$ with the rate function I under the topology of uniform convergence.*

Proof. According to Theorem 2.2, we only need to verify Condition 2.1, which will be done in the last section. \square

4. Tightness of $\mathcal{G}^\epsilon(\epsilon N^{\epsilon^{-1}} \varphi_\epsilon)$

The main result of this section is Proposition 4.1 in which we prove the tightness of the solutions \tilde{X}^ϵ of the controlled SPDEs (4.4). To this end, \tilde{X}^ϵ is written as the summation of three terms $Y^\epsilon + Z^\epsilon + M^\epsilon$, and their tightness are proved separately. In fact, the martingale part M^ϵ is proved to converge to 0 by an estimate of the H -norm of \tilde{X}^ϵ which is given in Lemma 4.4. The other two parts Z^ϵ and Y^ϵ are of finite variations, and their tightness follows from Ascoli-Arzelà's theorem and from Kolmogorov's criterion

respectively. The keys in applying these theorems are again in obtaining good estimates of the norms of \tilde{X}^ϵ . For Z^ϵ , the H -norm is again needed. However, for Y^ϵ , the V -norm is needed which is derived in Lemma 4.5. As auxiliary results before deriving estimates of Lemmas 4.4 and 4.5, we will state three lemmas whose proofs can be adopted from those in Budhiraja, A., Chen, J. and Dupuis, P. (2013), Yang, X., Zhai, J. and Zhang, T. (2015) and Budhiraja, A., Dupuis, P. and Maroulas, V. (2011).

Using similar arguments as those in proving (Budhiraja, A., Chen, J. and Dupuis, P., 2013, Lemma 3.4), we can establish the following lemma.

Lemma 4.1. *For any $h \in \mathcal{H}_p \cap L_{p'}(\nu_T)$, $p' \in (0, p]$, there exists a constant $C_{h,p,p',N}$ such that*

$$C_{h,p,p',N} := \sup_{g \in S^N} \int_{\mathbb{X}_T} h^{p'}(s, v)(g(s, v) + 1)\nu(dv)ds < \infty. \quad (4.1)$$

For any $h \in \mathcal{H}_2 \cap L_2(\nu_T)$, there exists a constant $C_{h,N}$ such that

$$C_{h,N} := \sup_{g \in S^N} \int_{\mathbb{X}_T} h(s, v)|g(s, v) - 1|\nu(dv)ds < \infty. \quad (4.2)$$

Using the argument used for proving (Budhiraja, A., Chen, J. and Dupuis, P., 2013, Lemmas 3.4 and 3.11) and (Yang, X., Zhai, J. and Zhang, T., 2015, (3.19)), we further get

Lemma 4.2. *Let $h : \mathbb{X}_T \rightarrow \mathbb{R}$ be a measurable function such that*

$$\int_{\mathbb{X}_T} |h(s, v)|^2 \nu(dv)ds < \infty,$$

and for all $\delta \in (0, \infty)$

$$\int_E \exp(\delta|h(s, v)|)\nu(dv)ds < \infty,$$

for all $E \in \mathcal{B}(\mathbb{X}_T)$ satisfying $\nu_T(E) < \infty$.

a). Fix $N \in \mathbb{N}$, and let $g_n, g \in S^N$ be such that $g_n \rightarrow g$ as $n \rightarrow \infty$. Then

$$\lim_{n \rightarrow \infty} \int_{\mathbb{X}_T} h(s, v)(g_n(s, v) - 1)\nu(dv)ds = \int_{\mathbb{X}_T} h(s, v)(g(s, v) - 1)\nu(dv)ds;$$

b). Fix $N \in \mathbb{N}$. Given $\epsilon > 0$, there exists a compact set $K_\epsilon \subset \mathbb{X}$, such that

$$\sup_{g \in S^N} \int_{[0, T]} \int_{K_\epsilon^c} |h(s, v)||g(s, v) - 1|\nu(dv)ds \leq \epsilon.$$

c). For every $\eta > 0$, there exists $\delta > 0$, we have such that for any $A \in \mathcal{B}([0, T])$ satisfying $\lambda_T(A) < \delta$

$$\sup_{g \in S^N} \int_A \int_{\mathbb{X}} h(s, v) |g(s, v) - 1| \nu(dv) ds \leq \eta. \quad (4.3)$$

Fix $N \in \mathbb{N}$. For any $\varphi_\epsilon \in \tilde{\mathbb{A}}^N$, consider the following controlled SPDEs

$$\begin{aligned} d\tilde{X}_t^\epsilon &= \mathcal{A}(t, \tilde{X}_t^\epsilon) dt + \int_{\mathbb{X}} f(t, \tilde{X}_t^\epsilon, z) (\varphi_\epsilon(t, z) - 1) \nu(dz) dt \\ &\quad + \epsilon \int_{\mathbb{X}} f(t, \tilde{X}_{t-}^\epsilon, z) \tilde{N}^{\epsilon^{-1}\varphi_\epsilon}(dz, dt), \end{aligned} \quad (4.4)$$

with initial condition $\tilde{X}_0^\epsilon = x$.

Recall $\tilde{\mathbb{A}}^N$ in Theorem 2.2. Let $\vartheta_\epsilon = \frac{1}{\varphi_\epsilon}$. The following lemma follows from Lemma 2.3 and Section 5.2 in [Budhiraja, A., Dupuis, P. and Maroulas, V. \(2011\)](#). Recall the notations in Section 2.1, we have

Lemma 4.3.

$$\begin{aligned} \mathcal{E}_t^\epsilon(\vartheta_\epsilon) &:= \exp \left\{ \int_{(0,t] \times \mathbb{X} \times [0, \epsilon^{-1}\varphi_\epsilon]} \log(\vartheta_\epsilon(s, x)) \bar{N}(ds dx dr) \right. \\ &\quad \left. + \int_{(0,t] \times \mathbb{X} \times [0, \epsilon^{-1}\varphi_\epsilon]} (-\vartheta_\epsilon(s, x) + 1) \bar{\nu}_T(ds dx dr) \right\} \end{aligned}$$

Consequently,

$$\mathbb{Q}_t^\epsilon(G) = \int_G \mathcal{E}_t^\epsilon(\vartheta_\epsilon) d\bar{\mathbb{P}}, \quad \text{for } G \in \mathcal{B}(\bar{\mathbb{M}})$$

defines a probability measure on $\bar{\mathbb{M}}$.

By the fact that $\epsilon N^{\epsilon^{-1}\varphi_\epsilon}$ under \mathbb{Q}_T^ϵ has the same law as that of $\epsilon N^{\epsilon^{-1}}$ under $\bar{\mathbb{P}}$. From Theorem 1.1, we see that there exists a unique solution \tilde{X}^ϵ to the controlled SPDE (4.4) which satisfies (2) in Theorem 1.1.

By the definition of \mathcal{G}^ϵ , we have

$$\tilde{X}^\epsilon = \mathcal{G}^\epsilon(\epsilon N^{\epsilon^{-1}\varphi_\epsilon}). \quad (4.5)$$

The following estimates (Lemmas 4.4 and 4.5) will be useful.

Lemma 4.4. For $p = 2, 2 + \beta$ or Υ in (H5), there exists $\epsilon_p, C_p > 0$ such that

$$\sup_{\epsilon \in (0, \epsilon_p]} \mathbb{E} \left(\sup_{t \in [0, T]} \|\tilde{X}_t^\epsilon\|_H^p \right) + \mathbb{E} \left(\int_0^T \|\tilde{X}_t^\epsilon\|_H^{p-2} \|\tilde{X}_t^\epsilon\|_V^\alpha dt \right) \leq C_p.$$

Proof. By Itô's formula, we have

$$\|\tilde{X}_t^\epsilon\|_H^p = \|x\|_H^p + I_1(t) + I_2(t) + I_3(t) + I_4(t), \quad (4.6)$$

where

$$\begin{aligned} I_1(t) &= \frac{p}{2} \int_0^t \|\tilde{X}_s^\epsilon\|_H^{p-2} \left(2 \langle \mathcal{A}(s, \tilde{X}_s^\epsilon), \tilde{X}_s^\epsilon \rangle_{V^*, V} \right) ds, \\ I_2(t) &= \int_0^t \int_{\mathbb{X}} p \|\tilde{X}_{s-}^\epsilon\|_H^{p-2} \langle \epsilon f(s, \tilde{X}_{s-}^\epsilon, z), \tilde{X}_{s-}^\epsilon \rangle_{H, H} \tilde{N}^{\epsilon^{-1} \varphi_\epsilon}(dz, ds), \\ I_4(t) &= \int_0^t \int_{\mathbb{X}} \left[\|\tilde{X}_{s-}^\epsilon + \epsilon f(s, \tilde{X}_{s-}^\epsilon, z)\|_H^p - \|\tilde{X}_{s-}^\epsilon\|_H^p \right. \\ &\quad \left. - p \|\tilde{X}_{s-}^\epsilon\|_H^{p-2} \langle \epsilon f(s, \tilde{X}_{s-}^\epsilon, z), \tilde{X}_{s-}^\epsilon \rangle_{H, H} \right] N^{\epsilon^{-1} \varphi_\epsilon}(dz, ds), \end{aligned}$$

and

$$I_4(t) = p \int_0^t \|\tilde{X}_s^\epsilon\|_H^{p-2} \langle \int_{\mathbb{X}} f(s, \tilde{X}_s^\epsilon, z) (\varphi_\epsilon(s, z) - 1), \tilde{X}_s^\epsilon \rangle_{H, H} \nu(dz) ds.$$

Note that by (H3),

$$\begin{aligned} I_1(t) &\leq \frac{p}{2} \int_0^t \|\tilde{X}_s^\epsilon\|_H^{p-2} \left(F_s + F_s \|\tilde{X}_s^\epsilon\|_H^2 - \theta \|\tilde{X}_s^\epsilon\|_V^\alpha \right) ds \\ &\leq -\frac{\theta p}{2} \int_0^t \|\tilde{X}_s^\epsilon\|_H^{p-2} \|\tilde{X}_s^\epsilon\|_V^\alpha ds + \frac{p}{2} \int_0^t \left[\left(\|\tilde{X}_s^\epsilon\|_H^p + 1 \right) F_s + F_s \|\tilde{X}_s^\epsilon\|_H^p \right] ds \\ &\leq -\frac{\theta p}{2} \int_0^t \|\tilde{X}_s^\epsilon\|_H^{p-2} \|\tilde{X}_s^\epsilon\|_V^\alpha ds + \frac{p}{2} \int_0^t F_s ds + \int_0^t p F_s \|\tilde{X}_s^\epsilon\|_H^p ds, \end{aligned} \quad (4.7)$$

and by (H5),

$$\begin{aligned} I_4(t) &\leq p \int_0^t \|\tilde{X}_s^\epsilon\|_H^{p-1} \int_{\mathbb{X}} |f(s, \tilde{X}_s^\epsilon, z)|_H |(\varphi_\epsilon(s, z) - 1)| \nu(dz) ds \\ &\leq p \int_0^t \|\tilde{X}_s^\epsilon\|_H^{p-1} (1 + \|\tilde{X}_s^\epsilon\|_H) \int_{\mathbb{X}} L_f(s, z) |(\varphi_\epsilon(s, z) - 1)| \nu(dz) ds \\ &\leq p \int_0^t \int_{\mathbb{X}} L_f(s, z) |(\varphi_\epsilon(s, z) - 1)| \nu(dz) ds \\ &\quad + 2p \int_0^t \|\tilde{X}_s^\epsilon\|_H^p \int_{\mathbb{X}} L_f(s, z) |(\varphi_\epsilon(s, z) - 1)| \nu(dz) ds. \end{aligned} \quad (4.8)$$

By Gronwall's inequality, combining (4.6) (4.7), (4.8) and Lemma 4.1,

$$\begin{aligned}
& \|\tilde{X}_t^\epsilon\|_H^p + \frac{\theta p}{2} \int_0^t \|\tilde{X}_s^\epsilon\|_H^{p-2} \|\tilde{X}_s^\epsilon\|_V^\alpha ds \\
& \leq \exp\left(p \int_0^T F_s ds + 2pC_{L_f, N}\right) \times \left(\|x\|_H^p + \frac{p}{2} \int_0^T F_s ds + \sup_{s \in [0, t]} |I_2(s)| + pC_{L_f, N}\right. \\
& \quad \left. + \int_0^t \int_{\mathbb{X}} c_p \left(\|\tilde{X}_{s-}^\epsilon\|_H^{p-2} \|\epsilon f(s, \tilde{X}_{s-}^\epsilon, z)\|_H^2 + \|\epsilon f(s, \tilde{X}_{s-}^\epsilon, z)\|_H^p\right) N^{\epsilon^{-1}\varphi_\epsilon}(dz, ds)\right),
\end{aligned} \tag{4.9}$$

we have used (4.9) in Brzeźniak, Z., Liu, W. and Zhu, J. (2014) to I_3 , i.e.

$$\left| \|x+h\|_H^p - \|x\|_H^p - p\|x\|_H^{p-2} \langle x, h \rangle_{H, H} \right| \leq c_p \left(\|x\|_H^{p-2} \|h\|_H^2 + \|h\|_H^p \right), \quad \forall x, h \in H.$$

By Lemma 4.1, we have

$$\begin{aligned}
& \mathbb{E} \left(\sup_{s \in [0, T]} |I_2(s)| \right) \\
& \leq \mathbb{E} \left(\int_0^T \int_{\mathbb{X}} \epsilon^2 p^2 \|\tilde{X}^\epsilon(s-)\|_H^{2p-4} \langle f(s, \tilde{X}_{s-}^\epsilon, z), \tilde{X}^\epsilon(s-) \rangle_{H, H}^2 N^{\epsilon^{-1}\varphi_\epsilon}(dz, ds) \right)^{1/2} \\
& \leq \mathbb{E} \left(\int_0^T \int_{\mathbb{X}} \epsilon^2 p^2 \|\tilde{X}^\epsilon(s-)\|_H^{2p-2} L_f^2(s, z) \left(\|\tilde{X}_{s-}^\epsilon\|_H + 1 \right)^2 N^{\epsilon^{-1}\varphi_\epsilon}(dz, ds) \right)^{1/2} \\
& \leq \mathbb{E} \left(\sup_{s \in [0, T]} \|\tilde{X}_s^\epsilon\|_H^p \cdot \epsilon^2 p^2 \int_0^T \int_{\mathbb{X}} \|\tilde{X}_{s-}^\epsilon\|_H^{p-2} L_f^2(s, z) \left(\|\tilde{X}_{s-}^\epsilon\|_H + 1 \right)^2 N^{\epsilon^{-1}\varphi_\epsilon}(dz, ds) \right)^{1/2} \\
& \leq \frac{1}{4} \mathbb{E} \left(\sup_{s \in [0, T]} \|\tilde{X}_s^\epsilon\|_H^p \right) \\
& \quad + 16\epsilon p^2 \mathbb{E} \left[\left(\sup_{s \in [0, T]} \|\tilde{X}_s^\epsilon\|_H^p + 1 \right) \int_0^T \int_{\mathbb{X}} L_f^2(s, z) \varphi_\epsilon(s, z) \nu(dz) ds \right] \\
& \leq \left(\frac{1}{4} + 16\epsilon p^2 C_{L_f, 2, 2, N} \right) \mathbb{E} \left(\sup_{s \in [0, T]} \|\tilde{X}_s^\epsilon\|_H^p \right) + 16\epsilon p^2 C_{L_f, 2, 2, N}.
\end{aligned} \tag{4.10}$$

On the other hand, by Lemma 4.1 again, we have

$$\begin{aligned}
& \mathbb{E} \left(\int_0^T \int_{\mathbb{X}} c_p \|\tilde{X}_s^\epsilon\|_H^{p-2} \|\epsilon f(s, \tilde{X}_s^\epsilon, z)\|_H^2 N^{\epsilon^{-1}\varphi_\epsilon}(dz, ds) \right) \\
& \leq \epsilon c_p \mathbb{E} \left(\int_0^T \int_{\mathbb{X}} \|\tilde{X}_s^\epsilon\|_H^{p-2} L_f^2(s, z) \left(\|\tilde{X}_s^\epsilon\|_H + 1 \right)^2 \varphi_\epsilon(s, z) \nu(dz) ds \right) \\
& \leq \epsilon c_p \mathbb{E} \left[\left(\sup_{s \in [0, T]} \|\tilde{X}_s^\epsilon\|_H^p + 1 \right) \int_0^T \int_{\mathbb{X}} L_f^2(s, z) \varphi_\epsilon(s, z) \nu(dz) ds \right] \\
& \leq \epsilon c_p C_{L_f, p, p, N} \mathbb{E} \left(\sup_{s \in [0, T]} \|\tilde{X}_s^\epsilon\|_H^p \right) + \epsilon c_p C_{L_f, 2, 2, N},
\end{aligned} \tag{4.11}$$

and

$$\begin{aligned}
& \mathbb{E} \left(\int_0^T \int_{\mathbb{X}} c_p \|\epsilon f(s, \tilde{X}_s^\epsilon, z)\|_H^p N^{\epsilon^{-1}\varphi_\epsilon}(dz, ds) \right) \\
&= \epsilon^{p-1} c_p \mathbb{E} \left(\int_0^T \int_{\mathbb{X}} \|f(s, \tilde{X}_s^\epsilon, z)\|_H^p \varphi_\epsilon(s, z) \nu(dz) ds \right) \\
&\leq \epsilon^{p-1} c_p \mathbb{E} \left[\left(\sup_{s \in [0, T]} \|\tilde{X}_s^\epsilon\|_H^p + 1 \right) \int_0^T \int_{\mathbb{X}} L_f^p(s, z) \varphi_\epsilon(s, z) \nu(dz) ds \right] \\
&\leq \epsilon^{p-1} c_p C_{L_f, p, p, N} \mathbb{E} \left(\sup_{s \in [0, T]} \|\tilde{X}_s^\epsilon\|_H^p \right) + \epsilon^{p-1} c_p C_{L_f, p, p, N}. \tag{4.12}
\end{aligned}$$

Combining (4.9)–(4.12), we obtain that there exists $\epsilon_p > 0$ such that

$$\sup_{\epsilon \in (0, \epsilon_p]} \left[\mathbb{E} \left(\sup_{s \in [0, T]} \|\tilde{X}_s^\epsilon\|_H^p \right) + \frac{\theta p}{2} \mathbb{E} \left(\int_0^T \|\tilde{X}_s^\epsilon\|_H^{p-2} \|\tilde{X}_s^\epsilon\|_V^\alpha ds \right) \right] \leq C_{N, p, T, \|x\|_H, \int_0^T F_s ds, L_f}.$$

The proof is complete. \square

Lemma 4.5. For $p = \frac{\gamma}{2}$, there exist C_p such that

$$\sup_{\epsilon \in (0, \epsilon_{2p})} \mathbb{E} \left(\int_0^T \|\tilde{X}_s^\epsilon\|_V^\alpha ds \right)^p \leq C_p.$$

Here ϵ_{2p} comes from Lemma 4.4.

Proof. Consider $p = 2$ in (4.9), we have

$$\theta \int_0^t \|\tilde{X}_s^\epsilon\|_V^\alpha ds \leq C_{N, T, \int_0^T F_s ds, L_f} \left(\|x\|_H^2 + \int_0^T F_s ds + \sup_{s \in [0, t]} |I_2(s)| + 2C_{L_f, N} + J(t) \right), \tag{4.13}$$

where

$$J(t) = \int_0^t \int_{\mathbb{X}} c_2 \left(\|\epsilon f(s, \tilde{X}_{s-}^\epsilon, z)\|_H^2 \right) N^{\epsilon^{-1}\varphi_\epsilon}(dz, ds).$$

In the following calculations, we take $p = \frac{\gamma}{2}$. Note that

$$\begin{aligned}
\mathbb{E}(|J(t)|^p) &\leq c_p \mathbb{E} \left(\left| \int_0^T \int_{\mathbb{X}} \left(\|\epsilon f(s, \tilde{X}_{s-}^\epsilon, z)\|_H^2 \right) \tilde{N}^{\epsilon^{-1}\varphi_\epsilon}(dz, ds) \right|^p \right) \\
&\quad + c_p \mathbb{E} \left(\left| \int_0^T \int_{\mathbb{X}} \left(\epsilon \|f(s, \tilde{X}_s^\epsilon, z)\|_H^2 \right) \varphi_\epsilon(s, z) \nu(dz) ds \right|^p \right).
\end{aligned}$$

By Kunita's first inequality (refer to Theorem 4.4.23 in [Applebaum, D. \(2004\)](#)), we can continue with

$$\begin{aligned} \mathbb{E}(|J(t)|^p) &\leq c_p \epsilon^{2p-1} \mathbb{E} \left(\int_0^T \int_{\mathbb{X}} \|f(s, \tilde{X}_s^\epsilon, z)\|_H^{2p} \varphi_\epsilon(s, z) \nu(dz) ds \right) \\ &\quad + c_p \epsilon^{3p/2} \mathbb{E} \left(\int_0^T \int_{\mathbb{X}} \|f(s, \tilde{X}_s^\epsilon, z)\|_H^4 \varphi_\epsilon(s, z) \nu(dz) ds \right)^{p/2} \\ &\quad + c_p \epsilon^p \mathbb{E} \left(\int_0^T \int_{\mathbb{X}} \|f(s, \tilde{X}_s^\epsilon, z)\|_H^2 \varphi_\epsilon(s, z) \nu(dz) ds \right)^p. \end{aligned}$$

Thus, by Lemma 4.1, we have

$$\begin{aligned} &\mathbb{E}(|J(t)|^p) \tag{4.14} \\ &\leq c_p \mathbb{E} \left(1 + \sup_{s \in [0, T]} \|\tilde{X}_s^\epsilon\|_H \right)^{2p} \left(\epsilon^{2p-1} \sup_{\varphi \in S^N} \int_0^T \int_{\mathbb{X}} L_f^{2p}(s, z) \varphi(s, z) \nu(dz) ds \right. \\ &\quad \left. + \epsilon^{3p/2} \left(\sup_{\varphi \in S^N} \int_0^T \int_{\mathbb{X}} L_f^4(s, z) \varphi(s, z) \nu(dz) ds \right)^{p/2} \right. \\ &\quad \left. + \epsilon^p \left(\sup_{\varphi \in S^N} \int_0^T \int_{\mathbb{X}} L_f^2(s, z) \varphi(s, z) \nu(dz) ds \right)^p \right) \\ &\leq c_p \mathbb{E} \left(1 + \sup_{s \in [0, T]} \|\tilde{X}_s^\epsilon\| \right)^{2p} \left(\epsilon^{2p-1} C_{L_f, 2p, 2p, N} + \epsilon^{3p/2} \left(C_{L_f, 4, 4, N} \right)^{p/2} + \epsilon^p \left(C_{L_f, 2, 2, N} \right)^p \right). \end{aligned}$$

By Kunita's first inequality again,

$$\begin{aligned} &\mathbb{E} \left(\sup_{s \in [0, T]} |I_2(s)|^p \right) \\ &\leq c_p \epsilon^{p-1} \mathbb{E} \left(\int_0^T \int_{\mathbb{X}} \left| \langle f(s, \tilde{X}_s^\epsilon, z), \tilde{X}_s^\epsilon \rangle_{H, H} \right|^p \varphi_\epsilon(s, z) \nu(dz) ds \right) \\ &\quad + c_p \epsilon^{p/2} \mathbb{E} \left(\int_0^T \int_{\mathbb{X}} \left| \langle f(s, \tilde{X}_s^\epsilon, z), \tilde{X}_s^\epsilon \rangle_{H, H} \right|^2 \varphi_\epsilon(s, z) \nu(dz) ds \right)^{p/2} \\ &\leq c_p \epsilon^{p-1} \mathbb{E} \left(\int_0^T \int_{\mathbb{X}} \|\tilde{X}_s^\epsilon\|_H^p L_f^p(s, z) \left(1 + \|\tilde{X}_s^\epsilon\|_H \right)^p \varphi_\epsilon(s, z) \nu(dz) ds \right) \\ &\quad + c_p \epsilon^{p/2} \mathbb{E} \left(\int_0^T \int_{\mathbb{X}} \|\tilde{X}_s^\epsilon\|_H^2 L_f^2(s, z) \left(1 + \|\tilde{X}_s^\epsilon\|_H \right)^2 \varphi_\epsilon(s, z) \nu(dz) ds \right)^{p/2} \\ &\leq c_p \epsilon^{p-1} \mathbb{E} \left(1 + \sup_{s \in [0, T]} \|\tilde{X}_s^\epsilon\|_H \right)^{2p} \sup_{\varphi \in S^N} \int_0^T \int_{\mathbb{X}} L_f^p(s, z) \varphi(s, z) \nu(dz) ds \\ &\quad + c_p \epsilon^{p/2} \mathbb{E} \left(1 + \sup_{s \in [0, T]} \|\tilde{X}_s^\epsilon\|_H \right)^{2p} \left(\sup_{\varphi \in S^N} \int_0^T \int_{\mathbb{X}} L_f^2(s, z) \varphi(s, z) \nu(dz) ds \right)^{p/2} \\ &\leq c_p \mathbb{E} \left(1 + \sup_{s \in [0, T]} \|\tilde{X}_s^\epsilon\| \right)^{2p} \left(\epsilon^{p-1} C_{L_f, p, p, N} + \epsilon^{p/2} \left(C_{L_f, 2, 2, N} \right)^{p/2} \right). \tag{4.15} \end{aligned}$$

Lemma 4.4 and (4.13)–(4.15) imply this lemma. \square

Finally, we prove the tightness of $\{\tilde{X}^\epsilon\}$.

Proposition 4.1. *For some $\epsilon_0 > 0$, $\{\tilde{X}^\epsilon\}_{\epsilon \in (0, \epsilon_0]}$ is tight in $D([0, T], V^*)$ with the Skorohod topology. Moreover, set*

$$\begin{aligned} M_t^\epsilon &= \int_0^t \int_{\mathbb{X}} \epsilon f(s, \tilde{X}_{s-}^\epsilon, z) \tilde{N}^{\epsilon^{-1} \varphi_\epsilon}(dz, ds), \\ Z_t^\epsilon &= \int_0^t \int_{\mathbb{X}} f(s, \tilde{X}_s^\epsilon, z) (\varphi_\epsilon(s, z) - 1) \nu(dz) ds, \\ Y_t^\epsilon &= \int_0^t \mathcal{A}(s, \tilde{X}_s^\epsilon) ds, \end{aligned}$$

then

- (a) $\lim_{\epsilon \rightarrow 0} \mathbb{E} \left(\sup_{t \in [0, T]} \|M_t^\epsilon\|_H^2 \right) = 0$,
- (b) $(Z_t^\epsilon)_{0 \leq t \leq T}$ is tight in $C([0, T], V^*)$,
- (c) $(Y_t^\epsilon)_{0 \leq t \leq T}$ is tight in $C([0, T], V^*)$.

Proof. (a). By Lemma 4.1, we have

$$\begin{aligned} & \mathbb{E} \left(\sup_{t \in [0, T]} \|M_t^\epsilon\|_H^2 \right) \\ & \leq C\epsilon \mathbb{E} \left(\int_0^T \int_{\mathbb{X}} \|f(s, \tilde{X}_s^\epsilon, z)\|_H^2 \varphi_\epsilon(s, z) \nu(dz) ds \right) \\ & \leq C\epsilon \mathbb{E} \left(\int_0^T \int_{\mathbb{X}} L_f^2(s, z) \left(1 + \|\tilde{X}_s^\epsilon\|_H\right)^2 \varphi_\epsilon(s, z) \nu(dz) ds \right) \\ & \leq C\epsilon \mathbb{E} \left(1 + \sup_{s \in [0, T]} \|\tilde{X}_s^\epsilon\|_H \right)^2 \left(\sup_{\varphi \in S^N} \int_0^T \int_{\mathbb{X}} L_f^2(s, z) \varphi(s, z) \nu(dz) ds \right) \\ & \leq C\epsilon \mathbb{E} \left(1 + \sup_{s \in [0, T]} \|\tilde{X}_s^\epsilon\|_H \right)^2 C_{L_f, 2, 2, N} \\ & \rightarrow 0, \text{ as } \epsilon \rightarrow 0. \end{aligned} \tag{4.16}$$

(b). It is sufficient to prove that for any $\delta > 0$, there exists a compact subset $K_\delta \subset C([0, T], V^*)$ such that

$$\bar{\mathbb{P}}(Z^\epsilon \in K_\delta) > 1 - \delta.$$

Denote

$$\mathcal{D}_{M, N} = \left\{ (r_t, g_t) : r. \in D([0, T], H) \cap L^\alpha([0, T], V), \sup_{t \in [0, T]} \|r_t\|_H \leq M; g \in S^N \right\},$$

$$\mathcal{R}(\mathcal{D}_{M,N}) = \left\{ y. = \int_0^\cdot \int_{\mathbb{X}} f(s, r_s, z)(g(s, z) - 1)\nu(dz)ds, \quad (r, g) \in \mathcal{D}_{M,N} \right\}.$$

For any $y \in \mathcal{R}(\mathcal{D}_{M,N})$, we have

$$\begin{aligned} \|y_t - y_s\|_H &\leq \int_s^t \int_{\mathbb{X}} \|f(l, r(l), z)\|_H |g(l, z) - 1| \nu(dz) dl \\ &\leq \sup_{l \in [s, t]} (1 + \|r(l)\|_H) \int_s^t \int_{\mathbb{X}} L_f(l, z) |g(l, z) - 1| \nu(dz) dl \\ &\leq (M+1) \sup_{\varphi \in S^N} \int_s^t \int_{\mathbb{X}} L_f(l, z) |\varphi(l, z) - 1| \nu(dz) dl. \end{aligned} \quad (4.17)$$

Applying Lemma 4.1, c) in Lemma 4.2 and (4.17), we obtain the following:

(1) for any $\eta > 0$, there exists $\varpi > 0$ (independent on y) such that for any $s, t \in [0, T]$ and $|t - s| \leq \varpi$

$$\|y_t - y_s\|_H \leq \eta, \quad \forall y \in \mathcal{R}(\mathcal{D}_{M,N}),$$

(2)

$$\sup_{y \in \mathcal{R}(\mathcal{D}_{M,N})} \sup_{t \in [0, T]} \|y_t\|_H = \sup_{y \in \mathcal{R}(\mathcal{D}_{M,N})} \sup_{t \in [0, T]} \|y_t - y_0\|_H \leq (M+1)C_{L_f, N}.$$

Since $V \hookrightarrow H$ is compact, we also have $H \hookrightarrow V^*$ compactly. By Ascoli-Arzelá's theorem, the complement of $\mathcal{R}(\mathcal{D}_{M,N})$ in $C([0, T], V^*)$, denoted by $\overline{\mathcal{R}}(\mathcal{D}_{M,N})$, is a compact subset in $C([0, T], V^*)$.

On the other hand,

$$\begin{aligned} \overline{\mathbb{P}}(Z^\epsilon \in \overline{\mathcal{R}}(\mathcal{D}_{M,N})) &\geq \overline{\mathbb{P}}\left(\sup_{t \in [0, T]} \|\tilde{X}_t^\epsilon\|_H \leq M\right) \\ &= 1 - \overline{\mathbb{P}}\left(\sup_{t \in [0, T]} \|\tilde{X}_t^\epsilon\|_H > M\right) \\ &\geq 1 - \mathbb{E}\left(\sup_{t \in [0, T]} \|\tilde{X}_t^\epsilon\|_H^2\right)/M^2 \\ &\geq 1 - C_2/M^2, \end{aligned}$$

we have applied Lemma 4.4 in the last inequality and this establishes that $\{Z^\epsilon\}$ is tight in $C([0, T], V^*)$.

(c). By Lemmas 4.4 and 4.5, recall η_0 in (H5), let $p = \alpha + \eta_0$, we have

$$\begin{aligned}
\mathbb{E}\|Y_t^\epsilon - Y_s^\epsilon\|_{V^*}^p &\leq \mathbb{E}\left|\int_s^t \|\mathcal{A}(l, \tilde{X}_l^\epsilon)\|_{V^*} dl\right|^p \\
&\leq |t-s|^{p/\alpha} \mathbb{E}\left(\int_s^t \|\mathcal{A}(l, \tilde{X}_l^\epsilon)\|_{V^*}^{\frac{\alpha}{\alpha-1}} dl\right)^{\frac{(\alpha-1)p}{\alpha}} \\
&\leq |t-s|^{p/\alpha} \mathbb{E}\left(\int_s^t (F_l + C\|\tilde{X}_l^\epsilon\|_V^\alpha)(1 + \|\tilde{X}_l^\epsilon\|_H^\beta) dl\right)^{\frac{(\alpha-1)p}{\alpha}} \\
&\leq |t-s|^{p/\alpha} \left[\mathbb{E}\left(\sup_{l \in [0, T]} (1 + \|\tilde{X}_l^\epsilon\|_H^\beta)^{\frac{2(\alpha-1)p}{\alpha}}\right)\right. \\
&\quad \left. + \mathbb{E}\left(\int_s^t F_l + C\|\tilde{X}_l^\epsilon\|_V^\alpha dl\right)^{\frac{2(\alpha-1)p}{\alpha}}\right] \\
&\leq C_{\alpha, p, F} |t-s|^{p/\alpha}.
\end{aligned}$$

Hence, a direct application of Kolmogorov's criterion, for every $\varpi \in (0, \frac{1}{\alpha} - \frac{1}{p})$, there exists constant C_ϖ independent on ϵ such that

$$\mathbb{E}\left(\sup_{t \neq s \in [0, T]} \frac{\|Y_t^\epsilon - Y_s^\epsilon\|_{V^*}^p}{|t-s|^{p\varpi}}\right) \leq C_\varpi. \quad (4.18)$$

On the other hand, by (4.4), we have

$$\tilde{X}_t^\epsilon = x + Y_t^\epsilon + Z_t^\epsilon + M_t^\epsilon.$$

Then

$$\begin{aligned}
&\mathbb{E}\left(\sup_{t \in [0, T]} \|Y_t^\epsilon\|_H^2\right) \quad (4.19) \\
&\leq C\left[\|x\|_H^2 + \mathbb{E}\left(\sup_{t \in [0, T]} \|\tilde{X}_t^\epsilon\|_H^2\right) + \mathbb{E}\left(\sup_{t \in [0, T]} \|Z_t^\epsilon\|_H^2\right) + \mathbb{E}\left(\sup_{t \in [0, T]} \|M_t^\epsilon\|_H^2\right)\right].
\end{aligned}$$

Notice that

$$\begin{aligned}
&\mathbb{E}\left(\sup_{t \in [0, T]} \|Z_t^\epsilon\|_H^2\right) \\
&\leq \mathbb{E}\left(\int_0^T \int_{\mathbb{X}} \|f(s, \tilde{X}_s^\epsilon, z)\|_H |\varphi_\epsilon(s, z) - 1| \nu(dz) ds\right)^2 \\
&\leq C\mathbb{E}\left(1 + \sup_{t \in [0, T]} \|\tilde{X}_t^\epsilon\|_H\right)^2 \left(\sup_{\varphi \in S^N} \int_0^T \int_{\mathbb{X}} L_f(s, z) |\varphi(s, z) - 1| \nu(dz) ds\right)^2 \\
&\leq CC_{L_f, N}^2 \mathbb{E}\left(1 + \sup_{t \in [0, T]} \|\tilde{X}_t^\epsilon\|_H\right)^2 \quad (4.20)
\end{aligned}$$

By Lemma 4.4, (4.19), (4.20) and (4.16), we have

$$\mathbb{E}\left(\sup_{t \in [0, T]} \|Y_t^\epsilon\|_H^2\right) \leq C < \infty, \quad (4.21)$$

where C is independent of ϵ .

For $\varpi \in (0, 1)$ and $R > 0$. Set

$$K_{R,\varpi} := \left\{ j \in C([0, T], V^*) : \sup_{t \in [0, T]} \|j_t\|_H + \sup_{s \neq t \in [0, T]} \frac{\|j_t - j_s\|_{V^*}}{|t - s|^\varpi} \leq R \right\}.$$

Since $V \hookrightarrow H$ is compact, we also have $H \hookrightarrow V^*$ compactly. By Ascoli-Arzelá's theorem, $K_{R,\varpi}$ is a compact subset of $C([0, T], V^*)$. By (4.18), (4.21) and Chebyshev's inequality, for some $\varpi \in (0, 1)$ and any $R > 0$, we have

$$\bar{\mathbb{P}}\left(Y^\epsilon \notin K_{R,\varpi}\right) \geq \frac{C_{T,\varpi}}{R}.$$

This implies the tightness of $\{Y^\epsilon\}$ in $C([0, T], V^*)$.

The tightness of $\{\tilde{X}^\epsilon\}$ in $D([0, T], V^*)$ then follows from (4.4) and the conclusions proved above. \square

5. Convergence of the processes

With the tightness result obtained in the last section, the main result of this section is to identify the limit of \tilde{X}^ϵ as the solution of the non-random equation (5.27). We use the three parts of \tilde{X}^ϵ we utilized in last section. As the limit of M^ϵ is 0, we only need to characterize the limits of the other two. Taking X as a limit point of \tilde{X}^ϵ , we first prove that Y^ϵ has a limit in Lemma 5.1, and then identify this limit with the desired form in Lemma 5.4 while Lemma 5.3 is a necessary preparation for Lemma 5.4. The limit of Z^ϵ with the desired form is identified in Lemma 5.2.

Throughout this section, we assume that for almost all ω , as $\epsilon \rightarrow 0$, $\varphi_\epsilon(\cdot, \cdot)(\omega)$ converges to $\varphi(\cdot, \cdot)(\omega)$ in S^N weakly, and $X^\epsilon(\omega)$ converges to $X(\omega)$ in $D([0, T], V^*)$ strongly with supremum norm.

Set

$$\begin{aligned} \mathcal{K} &= L^\alpha([0, T] \times \Omega \rightarrow V; dt \times \bar{\mathbb{P}}), \\ \mathcal{K}^* &= L^{\frac{\alpha}{\alpha-1}}([0, T] \times \Omega \rightarrow V^*; dt \times \bar{\mathbb{P}}). \end{aligned}$$

Lemma 5.1. *There exists a subsequence (ϵ_k) , $\bar{X} \in \mathcal{K} \cap L^\infty([0, T], L^{\beta+2}(\Omega, H))$ and $Y \in \mathcal{K}^*$ such that*

- (i) $X^{\epsilon_k} \rightarrow \bar{X}$ in \mathcal{K} weakly and in $L^\infty([0, T], L^{\beta+2}(\Omega, H))$ in weak-star topology,
- (ii) $\mathcal{A}(\cdot, X^{\epsilon_k}) \rightarrow Y$ in \mathcal{K}^* weakly,
- (iii)

$$\lim_{\epsilon \rightarrow 0} \mathbb{E} \left(\sup_{t \in [0, T]} \|X_t^\epsilon - X_t\|_{V^*} \right) = 0,$$

and for $m = \frac{\alpha}{\alpha+1}$,

$$\lim_{\epsilon \rightarrow 0} \mathbb{E} \int_0^T \|X_t^\epsilon - X_t\|_H^{2m} dt = 0.$$

Proof. (i) following from Lemma 4.4. For (ii), by Lemma 4.4 again,

$$\begin{aligned} \|\mathcal{A}(\cdot, X^\epsilon(\cdot))\|_{\mathcal{K}^*}^{\frac{\alpha-1}{\alpha}} &= \mathbb{E} \left(\int_0^T \|\mathcal{A}(t, X_t^\epsilon)\|_{V^*}^{\frac{\alpha-1}{\alpha}} dt \right) \\ &\leq \mathbb{E} \left(\int_0^T (F_t + C\|X_t^\epsilon\|_V^\alpha)(1 + \|X_t^\epsilon\|_H^\beta) dt \right) \\ &\leq C < \infty. \end{aligned} \quad (5.1)$$

Lemma 4.4 implies

$$\mathbb{E} \left(\sup_{t \in [0, T]} \|X_t^\epsilon\|_H^2 \right) \leq C_{2, N, x}, \quad (5.2)$$

and

$$\mathbb{E} \left(\int_0^T \|X_t^\epsilon\|_V^\alpha dt \right) \leq C. \quad (5.3)$$

Hence, by the strong convergence of $X^\epsilon(\omega)$ to $X(\omega)$ in $D([0, T], V^*)$ with sup norm, Fatou's lemma, (5.2) and (5.3), we have

$$\mathbb{E} \left(\sup_{t \in [0, T]} \|X_t\|_H^2 \right) \leq \liminf_{\epsilon \rightarrow 0} \mathbb{E} \left(\sup_{t \in [0, T]} \|X_t^\epsilon\|_H^2 \right) \leq C_{2, N, x}, \quad (5.4)$$

$$\mathbb{E} \left(\int_0^T \|X_t\|_V^\alpha dt \right) \leq \liminf_{\epsilon \rightarrow 0} \mathbb{E} \left(\int_0^T \|X_t^\epsilon\|_V^\alpha dt \right) \leq C. \quad (5.5)$$

and

$$\lim_{\epsilon \rightarrow 0} \mathbb{E} \left(\sup_{t \in [0, T]} \|X_t^\epsilon - X_t\|_{V^*} \right) = 0. \quad (5.6)$$

(5.6) can be seen as following. Set

$$\Omega_\delta^\epsilon = \{\omega : \sup_{t \in [0, T]} \|X_t^\epsilon - X_t\|_{V^*} \geq \delta\}.$$

The strong convergence of $X^\epsilon(\omega)$ to $X(\omega)$ in $D([0, T], V^*)$ with sup norm implies

$$\lim_{\epsilon \rightarrow 0} \bar{\mathbb{P}}(\Omega_\delta^\epsilon) = 0, \quad \forall \delta > 0. \quad (5.7)$$

Applying (5.7), (5.2) and (5.4) to (5.6), we have

$$\begin{aligned} &\lim_{\epsilon \rightarrow 0} \mathbb{E} \left(\sup_{t \in [0, T]} \|X_t^\epsilon - X_t\|_{V^*} \right) \\ &= \lim_{\epsilon \rightarrow 0} \left[\mathbb{E} \left(\sup_{t \in [0, T]} \|X_t^\epsilon - X_t\|_{V^*} \cdot 1_{\Omega_\delta^\epsilon} \right) + \mathbb{E} \left(\sup_{t \in [0, T]} \|X_t^\epsilon - X_t\|_{V^*} \cdot 1_{(\Omega_\delta^\epsilon)^c} \right) \right] \\ &\leq \delta + \lim_{\epsilon \rightarrow 0} \left(\mathbb{E} \left(\sup_{t \in [0, T]} \|X_t^\epsilon - X_t\|_{V^*}^2 \right) \right)^{1/2} \cdot \left(\bar{\mathbb{P}}(\Omega_\delta^\epsilon) \right)^{1/2} \\ &\leq \delta. \end{aligned}$$

The arbitrary of δ implies (5.6).

Taking $m = \frac{\alpha}{\alpha+1}$, we get

$$\begin{aligned} \mathbb{E} \int_0^T \|X_t^\epsilon - X_t\|_H^{2m} dt &= \mathbb{E} \int_0^T \langle X_t^\epsilon - X_t, X_t^\epsilon - X_t \rangle_{V^*, V}^m dt \\ &\leq \mathbb{E} \int_0^T \|X_t^\epsilon - X_t\|_{V^*}^m \|X_t^\epsilon - X_t\|_V^m dt \\ &\leq \left(\mathbb{E} \int_0^T \|X_t^\epsilon - X_t\|_{V^*} dt \right)^{\frac{\alpha-m}{\alpha}} \left(\mathbb{E} \int_0^T \|X_t^\epsilon - X_t\|_V^\alpha dt \right)^{\frac{m}{\alpha}}. \end{aligned}$$

Combining (5.3), (5.5) and (5.6), we have

$$\lim_{\epsilon \rightarrow 0} \mathbb{E} \int_0^T \|X_t^\epsilon - X_t\|_H^{2m} dt = 0. \quad (5.8)$$

□

Lemma 5.2. For any $h \in H$, we have

$$\begin{aligned} &\lim_{\epsilon_k \rightarrow 0} \left\langle \int_0^t \int_{\mathbb{X}} f(s, X_s^{\epsilon_k}, z) (\varphi_{\epsilon_k}(s, z) - 1) \nu(dz) ds, h \right\rangle_{H, H} \\ &= \left\langle \int_0^t \int_{\mathbb{X}} f(s, X_s, z) (\varphi(s, z) - 1) \nu(dz) ds, h \right\rangle_{H, H}. \end{aligned} \quad (5.9)$$

Proof. Denote $\zeta(s, z) = \langle f(s, X_s, z), h \rangle_{H, H}$. Since $\sup_{s \in [0, T]} \|X_s\|_H < \infty$, $\bar{\mathbb{P}}$ -a.s., and $L_f \in \mathcal{H}_2$, it follows from Remark 3.1 and Lemma 4.2 that

$$\begin{aligned} &\lim_{\epsilon_k \rightarrow 0} \left\langle \int_0^t \int_{\mathbb{X}} f(s, X_s, z) (\varphi_{\epsilon_k}(s, z) - 1) \nu(dz) ds, h \right\rangle_{H, H} \\ &= \left\langle \int_0^t \int_{\mathbb{X}} f(s, X_s, z) (\varphi(s, z) - 1) \nu(dz) ds, h \right\rangle_{H, H}. \end{aligned} \quad (5.10)$$

For any $\delta > 0$, denote $A_{\delta, \epsilon}(\omega) := \left\{ s \in [0, T] : \|X_s^\epsilon - X_s\|_H > \delta \right\}$. By (5.8)

$$\lim_{\epsilon \rightarrow 0} \mathbb{E} \left(\lambda_T(A_{\delta, \epsilon}) \right) \leq \frac{1}{\delta^{2m}} \lim_{\epsilon \rightarrow 0} \mathbb{E} \int_0^T \|X_t^\epsilon - X_t\|_H^{2m} dt = 0.$$

Therefore, there exists a subsequence ϵ_k (for simplicity, we still denote it by the same notation ϵ_k) such that

$$\lim_{\epsilon_k \rightarrow 0} \lambda_T(A_{\delta, \epsilon_k}) = 0, \quad \bar{\mathbb{P}}\text{-a.s.} \quad (5.11)$$

Applying Lemma 4.1, we have

$$\begin{aligned}
& \int_0^T \int_{\mathbb{X}} \|f(s, X_s^{\epsilon_k}, z) - f(s, X_s, z)\|_H |\varphi_{\epsilon_k}(s, z) - 1| \nu(dz) ds \\
& \leq \int_0^T \int_{\mathbb{X}} G_f(s, z) \|X_s^{\epsilon_k} - X_s\|_H |\varphi_{\epsilon_k}(s, z) - 1| \nu(dz) ds \\
& \leq \delta \int_{A_{\delta, \epsilon_k}^c} \int_{\mathbb{X}} G_f(s, z) |\varphi_{\epsilon_k}(s, z) - 1| \nu(dz) ds \\
& \quad + \sup_{s \in [0, T]} \|X_s^{\epsilon_k} - X_s\|_H \int_{A_{\delta, \epsilon_k}} \int_{\mathbb{X}} G_f(s, z) |\varphi_{\epsilon_k}(s, z) - 1| \nu(dz) ds \\
& \leq \delta \sup_{\varphi \in S^N} \int_0^T \int_{\mathbb{X}} G_f(s, z) |\varphi(s, z) - 1| \nu(dz) ds \\
& \quad + \sup_{s \in [0, T]} \|X_s^{\epsilon_k} - X_s\|_H \sup_{\varphi \in S^N} \int_{A_{\delta, \epsilon_k}} \int_{\mathbb{X}} G_f(s, z) |\varphi(s, z) - 1| \nu(dz) ds \quad (5.12) \\
& \leq \delta C_{G_f, N} + \sup_{s \in [0, T]} \|X_s^{\epsilon_k} - X_s\|_H \sup_{\varphi \in S^N} \int_{A_{\delta, \epsilon_k}} \int_{\mathbb{X}} G_f(s, z) |\varphi(s, z) - 1| \nu(dz) ds.
\end{aligned}$$

Notice that

$$\begin{aligned}
& \mathbb{E} \left(\sup_{s \in [0, T]} \|X_s^{\epsilon_k} - X_s\|_H \sup_{\varphi \in S^N} \int_{A_{\delta, \epsilon_k}} \int_{\mathbb{X}} G_f(s, z) |\varphi(s, z) - 1| \nu(dz) ds \right) \quad (5.13) \\
& \leq \left(\mathbb{E} \left(\sup_{s \in [0, T]} \|X_s^{\epsilon_k} - X_s\|_H^2 \right) \right)^{\frac{1}{2}} \left(\mathbb{E} \left(\sup_{\varphi \in S^N} \int_{A_{\delta, \epsilon_k}} \int_{\mathbb{X}} G_f(s, z) |\varphi(s, z) - 1| \nu(dz) ds \right)^2 \right)^{\frac{1}{2}}.
\end{aligned}$$

By the dominated convergence theorem, Lemma 4.2 c) and Lemma 4.1, we have

$$\lim_{\epsilon_k \rightarrow 0} \mathbb{E} \left(\sup_{\varphi \in S^N} \int_{A_{\delta, \epsilon_k}} \int_{\mathbb{X}} G_f(s, z) |\varphi(s, z) - 1| \nu(dz) ds \right)^2 = 0. \quad (5.14)$$

Hence, (5.2), (5.4), (5.12)-(5.14) imply

$$\lim_{\epsilon_k \rightarrow 0} \mathbb{E} \left(\int_0^T \int_{\mathbb{X}} \|f(s, X_s^{\epsilon_k}, z) - f(s, X_s, z)\|_H |\varphi_{\epsilon_k}(s, z) - 1| \nu(dz) ds \right) = 0. \quad (5.15)$$

So, there exists a subsequence ϵ_k (for simplicity, we still denote it by the same notation ϵ_k) such that

$$\lim_{\epsilon_k \rightarrow 0} \int_0^T \int_{\mathbb{X}} \|f(s, X_s^{\epsilon_k}, z) - f(s, X_s, z)\|_H |\varphi_{\epsilon_k}(s, z) - 1| \nu(dz) ds = 0, \quad \bar{\mathbb{P}}\text{-a.s.}$$

Combining this with (5.10), we arrive at (5.9). \square

Define

$$\tilde{X}_t := x + \int_0^t Y_s ds + \int_0^t \int_{\mathbb{X}} f(s, X_s, z)(\varphi(s, z) - 1)\nu(dz) ds. \quad (5.16)$$

By taking weak limit of (4.4), it is not difficulty to see that

$$\tilde{X}_t(\omega) = \bar{X}_t(\omega) = X_t(\omega), \text{ for } dt \times \bar{\mathbb{P}}\text{-almost all } (t, \omega).$$

Set

$$\mathcal{N} := \left\{ \phi : \phi \text{ is a } V\text{-valued } \bar{\mathcal{F}}_t\text{-adapted process such that } \mathbb{E} \left(\int_0^T \rho(\phi_s) ds \right) < \infty \right\}.$$

Fix $\phi \in \mathcal{K} \cap \mathcal{N} \cap L^\infty([0, T], L^{\beta+2}(\Omega, H))$ and $\psi \in L^\infty([0, T], \mathbb{R})$. Denote

$$\begin{aligned} G(X, \varphi, Y) &:= \mathbb{E} \left[\int_0^T \psi_t \int_0^t e^{-\int_0^s (K_l + \rho(\phi_l)) dl} \right. \\ &\quad \left. \times 2 \left\langle \int_{\mathbb{X}} f(s, X_s, z)(\varphi(s, z) - 1)\nu(dz), Y_s \right\rangle_{H, H} ds dt \right]. \end{aligned}$$

The following limiting result will be needed later.

Lemma 5.3.

$$\lim_{\epsilon_k \rightarrow 0} G(X^{\epsilon_k}, \varphi_{\epsilon_k}, X^{\epsilon_k}) = G(X, \varphi, X). \quad (5.17)$$

Proof. For any fixed $(t, \omega) \in [0, T] \times \Omega$. Set

$$\zeta(s, z) = \psi_t e^{-\int_0^s (K_l + \rho(\phi_l)) dl} \langle f(s, X_s, z), X_s \rangle_{H, H}.$$

By Lemma 4.2 and $\sup_{s \in [0, T]} \|X_s\|_H < \infty$ $\bar{\mathbb{P}}$ -a.s., we have $\forall (t, \omega) \in [0, T] \times \Omega$,

$$\begin{aligned} &\lim_{\epsilon_k \rightarrow 0} \psi_t \int_0^t e^{-\int_0^s (K_l + \rho(\phi_l)) dl} 2 \left\langle \int_{\mathbb{X}} f(s, X_s, z)(\varphi_{\epsilon_k}(s, z) - 1)\nu(dz), X_s \right\rangle_{H, H} ds \\ &= \psi_t \int_0^t e^{-\int_0^s (K_l + \rho(\phi_l)) dl} 2 \left\langle \int_{\mathbb{X}} f(s, X_s, z)(\varphi(s, z) - 1)\nu(dz), X_s \right\rangle_{H, H} ds. \end{aligned}$$

On the other hand, by Lemma 4.1

$$\begin{aligned} &\sup_{\varphi \in S^N} \left| \psi_t \left(\int_0^t e^{-\int_0^s (K_l + \rho(\phi_l)) dl} \left(2 \left\langle \int_{\mathbb{X}} f(s, X_s, z)(\varphi(s, z) - 1)\nu(dz), X_s \right\rangle_{H, H} \right) ds \right) \right| \\ &\leq C_\psi \sup_{\varphi \in S^N} \int_0^T \int_{\mathbb{X}} \|f(s, X_s, z)\|_H \|X_s\|_H |\varphi(s, z) - 1| \nu(dz) ds \\ &\leq C_\psi (1 + \sup_{s \in [0, T]} \|X_s\|_H)^2 \sup_{\varphi \in S^N} \int_0^T \int_{\mathbb{X}} L_f(s, z) |\varphi(s, z) - 1| \nu(dz) ds \\ &\leq C_{\psi, L_f, N} (1 + \sup_{s \in [0, T]} \|X_s\|_H)^2. \end{aligned}$$

By the dominated convergence theorem, we have

$$\lim_{\epsilon_k \rightarrow 0} G(X, \varphi_{\epsilon_k}, X) = G(X, \varphi, X). \quad (5.18)$$

Let $\delta > 0$. Recall

$$A_{\delta, \epsilon_k} := \left\{ s \in [0, T] : \|X_s^{\epsilon_k} - X_s\|_H > \delta \right\},$$

and (5.11) that is there exists a subsequence ϵ_k such that

$$\lim_{\epsilon_k \rightarrow 0} \lambda_T(A_{\delta, \epsilon_k}) = 0, \quad \bar{\mathbb{P}}\text{-a.s.}$$

Then we have

$$\begin{aligned} & \left| G(X^{\epsilon_k}, \varphi_{\epsilon_k}, X^{\epsilon_k}) - G(X^{\epsilon_k}, \varphi_{\epsilon_k}, X) \right| \\ & \leq C \mathbb{E} \left(\int_0^T \int_{\mathbb{X}} \|f(s, X_s^{\epsilon_k}, z)\|_H |\varphi_{\epsilon_k}(s, z) - 1| \|X_s^{\epsilon_k} - X_s\|_H \nu(dz) ds \right) \\ & \leq C \mathbb{E} \left(\int_0^T \int_{\mathbb{X}} L_f(s, z) (1 + \|X_s^{\epsilon_k}\|_H) |\varphi_{\epsilon_k}(s, z) - 1| \|X_s^{\epsilon_k} - X_s\|_H \nu(dz) ds \right) \\ & \leq C \delta \mathbb{E} \left(\int_{A_{\delta, \epsilon_k}^c} \int_{\mathbb{X}} L_f(s, z) (1 + \|X_s^{\epsilon_k}\|_H) |\varphi_{\epsilon_k}(s, z) - 1| \nu(dz) ds \right) \\ & \quad + C \mathbb{E} \left(\int_{A_{\delta, \epsilon_k}} \int_{\mathbb{X}} L_f(s, z) (1 + \|X_s^{\epsilon_k}\|_H) |\varphi_{\epsilon_k}(s, z) - 1| \|X_s^{\epsilon_k} - X_s\|_H \nu(dz) ds \right) \\ & \leq C \delta \mathbb{E} \left(\sup_{s \in [0, T]} (1 + \|X_s^{\epsilon_k}\|_H) \right) \sup_{\varphi \in S^N} \int_0^T \int_{\mathbb{X}} L_f(s, z) |\varphi(s, z) - 1| \nu(dz) ds \\ & \quad + C \mathbb{E} \left[\sup_{s \in [0, T]} \left((1 + \|X_s^{\epsilon_k}\|_H) (\|X_s^{\epsilon_k} - X_s\|_H) \right) \right. \\ & \quad \quad \left. \times \sup_{\varphi \in S^N} \int_{A_{\delta, \epsilon_k}} \int_{\mathbb{X}} L_f(s, z) |\varphi(s, z) - 1| \nu(dz) ds \right] \\ & \leq \delta C_{L_f, N} + C \left(\mathbb{E} \left(1 + \sup_{s \in [0, T]} \|X_s^{\epsilon_k}\|_H \right)^4 \right)^{1/4} \left(\mathbb{E} \left(1 + \sup_{s \in [0, T]} \|X_s^{\epsilon_k} - X_s\|_H \right)^4 \right)^{1/4} \\ & \quad \cdot \left(\mathbb{E} \left(\sup_{\varphi \in S^N} \int_{A_{\delta, \epsilon_k}} \int_{\mathbb{X}} L_f(s, z) |\varphi(s, z) - 1| \nu(dz) ds \right)^2 \right)^{1/2}. \end{aligned} \quad (5.19)$$

Similar as (5.14) and (5.15), we have

$$\lim_{\epsilon_k \rightarrow 0} \left| G(X^{\epsilon_k}, \varphi_{\epsilon_k}, X^{\epsilon_k}) - G(X^{\epsilon_k}, \varphi_{\epsilon_k}, X) \right| = 0. \quad (5.20)$$

On the other hand,

$$\begin{aligned}
& \left| G(X^{\epsilon_k}, \varphi_{\epsilon_k}, X) - G(X, \varphi_{\epsilon_k}, X) \right| \\
& \leq C\mathbb{E} \left(\int_0^T \int_{\mathbb{X}} \|f(s, X_s^{\epsilon_k}, z) - f(s, X_s, z)\|_H |\varphi_{\epsilon_k}(s, z) - 1| \|X_s\|_H \nu(dz) ds \right) \\
& \leq C\mathbb{E} \left(\int_0^T \int_{\mathbb{X}} G_f(s, z) \|X_s^{\epsilon_k} - X_s\|_H |\varphi_{\epsilon_k}(s, z) - 1| \|X_s\|_H \nu(dz) ds \right).
\end{aligned}$$

Using the similar arguments as proving (5.20), we have

$$\lim_{\epsilon_k \rightarrow 0} \left| G(X^{\epsilon_k}, \varphi_{\epsilon_k}, X) - G(X, \varphi_{\epsilon_k}, X) \right| = 0. \quad (5.21)$$

Combining (5.20), (5.21), and (5.18), we have (5.17). \square

Lemma 5.4.

$Y_t(\omega) = \mathcal{A}(t, X_t(\omega))$ for $dt \times \bar{\mathbb{P}}$ -almost all (t, ω) .

Proof. For $\phi \in \mathcal{K} \cap \mathcal{N} \cap L^\infty([0, T], L^{\beta+2}(\Omega, H))$, applying the Itô's formula,

$$\begin{aligned}
& e^{-\int_0^t (K_s + \rho(\phi_s)) ds} \|X_t^{\epsilon_k}\|_H^2 - \|x\|_H^2 \\
& = \int_0^t e^{-\int_0^s (K_l + \rho(\phi_l)) dl} \left[- (K_s + \rho(\phi_s)) \|X_s^{\epsilon_k}\|_H^2 + 2 \langle \mathcal{A}(s, X_s^{\epsilon_k}), X_s^{\epsilon_k} \rangle_{V^*, V} \right. \\
& \quad \left. + 2 \left\langle \int_{\mathbb{X}} f(s, X_s^{\epsilon_k}, z) (\varphi_{\epsilon_k}(s, z) - 1) \nu(dz), X_s^{\epsilon_k} \right\rangle_{H, H} \right] ds \\
& \quad + \int_0^t e^{-\int_0^s (K_l + \rho(\phi_l)) dl} \int_{\mathbb{X}} \left[2\epsilon_k \langle f(s, X_{s-}^{\epsilon_k}, z), X_{s-}^{\epsilon_k} \rangle_{H, H} \right] \tilde{N}^{\epsilon_k^{-1} \varphi_{\epsilon_k}}(ds, dz) \\
& \quad + \int_0^t e^{-\int_0^s (K_l + \rho(\phi_l)) dl} \int_{\mathbb{X}} \left[\epsilon_k^2 \|f(s, X_{s-}^{\epsilon_k}, z)\|_H^2 \right] N^{\epsilon_k^{-1} \varphi_{\epsilon_k}}(ds, dz).
\end{aligned}$$

Notice that

$$M_{\epsilon_k}(t) := \int_0^t e^{-\int_0^s (K_l + \rho(\phi_l)) dl} \int_{\mathbb{X}} \left[2\epsilon_k \langle f(s, X_{s-}^{\epsilon_k}, z), X_{s-}^{\epsilon_k} \rangle_{H, H} \right] \tilde{N}^{\epsilon_k^{-1} \varphi_{\epsilon_k}}(ds, dz)$$

is a square integrable martingale, we have

$$\begin{aligned}
& \mathbb{E}\left(e^{-\int_0^t (K_s + \rho(\phi_s)) ds} \|X_t^{\epsilon_k}\|_H^2\right) - \|x\|_H^2 \\
= & -\mathbb{E}\left(\int_0^t e^{-\int_0^s (K_l + \rho(\phi_l)) dl} (K_s + \rho(\phi_s)) \left(\|X_s^{\epsilon_k} - \phi_s\|_H^2 + 2\langle X_s^{\epsilon_k}, \phi_s \rangle_{H,H} - \|\phi_s\|_H^2\right) ds\right) \\
& +\mathbb{E}\left(\int_0^t e^{-\int_0^s (K_l + \rho(\phi_l)) dl} \left(2\langle \mathcal{A}(s, X_s^{\epsilon_k}) - \mathcal{A}(s, \phi_s), X_s^{\epsilon_k} - \phi_s \rangle_{V^*,V} \right. \right. \\
& \quad \left. \left. + 2\langle \mathcal{A}(s, \phi_s), X_s^{\epsilon_k} - \phi_s \rangle_{V^*,V} + 2\langle \mathcal{A}(s, X_s^{\epsilon_k}), \phi_s \rangle_{V^*,V}\right) ds\right) \\
& +\mathbb{E}\left(\int_0^t e^{-\int_0^s (K_l + \rho(\phi_l)) dl} \left(2\langle \int_{\mathbb{X}} f(s, X_s^{\epsilon_k}, z) (\varphi_{\epsilon_k}(s, z) - 1) \nu(dz), X_s^{\epsilon_k} \rangle_{H,H}\right) ds\right) \\
& +\mathbb{E}\left(\epsilon_k \int_0^t e^{-\int_0^s (K_l + \rho(\phi_l)) dl} \int_{\mathbb{X}} \|f(s, X_s^{\epsilon_k}, z)\|_H^2 \varphi_{\epsilon_k}(s, z) \nu(dz) ds\right) \\
\leq & -\mathbb{E}\left(\int_0^t e^{-\int_0^s (K_l + \rho(\phi_l)) dl} (K_s + \rho(\phi_s)) \left(2\langle X_s^{\epsilon_k}, \phi_s \rangle_{H,H} - \|\phi_s\|_H^2\right) ds\right) \\
& +\mathbb{E}\left(\int_0^t e^{-\int_0^s (K_l + \rho(\phi_l)) dl} \left(2\langle \mathcal{A}(s, \phi_s), X_s^{\epsilon_k} - \phi_s \rangle_{V^*,V} + 2\langle \mathcal{A}(s, X_s^{\epsilon_k}), \phi_s \rangle_{V^*,V}\right) ds\right) \\
& +\mathbb{E}\left(\int_0^t e^{-\int_0^s (K_l + \rho(\phi_l)) dl} \left(2\langle \int_{\mathbb{X}} f(s, X_s^{\epsilon_k}, z) (\varphi_{\epsilon_k}(s, z) - 1) \nu(dz), X_s^{\epsilon_k} \rangle_{H,H}\right) ds\right) \\
& +\mathbb{E}\left(\epsilon_k \int_0^t e^{-\int_0^s (K_l + \rho(\phi_l)) dl} \int_{\mathbb{X}} \|f(s, X_s^{\epsilon_k}, z)\|_H^2 \varphi_{\epsilon_k}(s, z) \nu(dz) ds\right). \tag{5.22}
\end{aligned}$$

By (i) of Lemma 5.1, we get

$$\begin{aligned}
& \mathbb{E}\left[\int_0^T \psi_t \left(e^{-\int_0^t (K_s + \rho(\phi_s)) ds} \|X_t\|_H^2 - \|x\|_H^2\right) dt\right] \\
\leq & \liminf_{\epsilon_k \rightarrow 0} \mathbb{E}\left[\int_0^T \psi_t \left(e^{-\int_0^t (K_s + \rho(\phi_s)) ds} \|X_t^{\epsilon_k}\|_H^2 - \|x\|_H^2\right) dt\right]. \tag{5.23}
\end{aligned}$$

By Lemma 4.1,

$$\begin{aligned}
& \mathbb{E}\left(\epsilon_k \int_0^t e^{-\int_0^s (K_l + \rho(\phi_l)) dl} \int_{\mathbb{X}} \|f(s, X_s^{\epsilon_k}, z)\|_H^2 \varphi_{\epsilon_k}(s, z) \nu(dz) ds\right) \\
\leq & \mathbb{E}\left(\epsilon_k \int_0^t \int_{\mathbb{X}} (1 + \|X_s^{\epsilon_k}\|_H)^2 L_f^2(s, z) \varphi_{\epsilon_k}(s, z) \nu(dz) ds\right) \\
\leq & \epsilon_k \mathbb{E}\left(\left(1 + \sup_{s \in [0, T]} \|X_s^{\epsilon_k}\|_H\right)^2\right) \sup_{\varphi \in \mathcal{S}^N} \int_0^T \int_{\mathbb{X}} L_f^2(s, z) \varphi(s, z) \nu(dz) ds \\
\leq & \epsilon_k C_{L_f, 2, 2, N}. \tag{5.24}
\end{aligned}$$

Combining from (5.22) to (5.24), and Lemma 5.3, we infer

$$\begin{aligned}
& \mathbb{E} \left[\int_0^T \psi_t \left(e^{-\int_0^t (K_s + \rho(\phi_s)) ds} \|X_t\|_H^2 - \|x\|_H^2 \right) dt \right] \\
\leq & -\mathbb{E} \left[\int_0^T \psi_t \int_0^t e^{-\int_0^s (K_l + \rho(\phi_l)) dl} (K_s + \rho(\phi_s)) \left(2\langle X_s, \phi_s \rangle_{H,H} - \|\phi_s\|_H^2 \right) ds dt \right] \\
& + \mathbb{E} \left[\int_0^T \psi_t \int_0^t e^{-\int_0^s (K_l + \rho(\phi_l)) dl} \left(2\langle \mathcal{A}(s, \phi_s), X_s - \phi_s \rangle_{V^*,V} + 2\langle Y_s, \phi_s \rangle_{V^*,V} \right) ds dt \right] \\
& + \mathbb{E} \left[\int_0^T \psi_t \int_0^t e^{-\int_0^s (K_l + \rho(\phi_l)) dl} \left(2\langle \int_{\mathbb{X}} f(s, X_s, z) (\varphi(s, z) - 1) \nu(dz), X_s \rangle_{H,H} \right) ds dt \right].
\end{aligned} \tag{5.25}$$

On the other hand, by (5.16), we have

$$\begin{aligned}
& \mathbb{E} \left(e^{-\int_0^t (K_s + \rho(\phi_s)) ds} \|X_t\|_H^2 - \|x\|_H^2 \right) \\
= & -\mathbb{E} \left(\int_0^t e^{-\int_0^s (K_l + \rho(\phi_l)) dl} (K_s + \rho(\phi_s)) \|X_s\|_H^2 ds \right) \\
& + \mathbb{E} \left(\int_0^t e^{-\int_0^s (K_l + \rho(\phi_l)) dl} 2\langle Y_s, X_s \rangle_{V^*,V} ds \right) \\
& + \mathbb{E} \left(\int_0^t e^{-\int_0^s (K_l + \rho(\phi_l)) dl} \left(2\langle \int_{\mathbb{X}} f(s, X_s, z) (\varphi(s, z) - 1) \nu(dz), X_s \rangle_{H,H} \right) ds \right).
\end{aligned} \tag{5.26}$$

By (5.25) and (5.26), we have

$$\begin{aligned}
& \mathbb{E} \left[\int_0^T \psi_t \int_0^t e^{-\int_0^s (K_l + \rho(\phi_l)) dl} \left(- (K_s + \rho(\phi_s)) \|X_s - \phi_s\|_H^2 \right. \right. \\
& \quad \left. \left. + 2\langle \mathcal{A}(s, \phi_s) - Y_s, X_s - \phi_s \rangle_{V^*,V} \right) ds dt \right] \leq 0.
\end{aligned}$$

Put $\phi = X - \eta \tilde{\phi} v$ for $\tilde{\phi} \in L^\infty([0, T] \times \Omega; dt \times \bar{\mathbb{P}}; \mathbb{R})$ and $v \in V$, divide both sides by η and let $\eta \rightarrow 0$, then we have

$$\mathbb{E} \left[\int_0^T \psi_t \int_0^t e^{-\int_0^s (K_l + \rho(\phi_l)) dl} \left(2\tilde{\phi}_s \langle \mathcal{A}(s, \phi_s) - Y_s, v \rangle_{V^*,V} \right) ds dt \right] \leq 0.$$

Hence $Y = \mathcal{A}(\cdot, X)$. □

Proposition 5.1. $X(\omega)$ solves the following equation:

$$X_t(\omega) = x + \int_0^t \mathcal{A}(s, X_s(\omega)) ds + \int_0^t \int_{\mathbb{X}} f(s, X_s(\omega), z) (\varphi(s, z)(\omega) - 1) \nu(dz) ds, \tag{5.27}$$

which has an unique solution in $C([0, T], H) \cap L^\alpha([0, T], V)$.

Proof. The equation (5.27) follows from Lemmas 5.1-5.4. The proof of the uniqueness is standard, and it is omitted. \square

Lemma 5.5. *There exists a subsequence ϖ_k , such that*

$$\lim_{\varpi_k \rightarrow 0} \sup_{t \in [0, T]} \|X_t^{\varpi_k} - X_t\|_H^2 = 0, \quad \bar{\mathbb{P}}\text{-a.s.} \quad (5.28)$$

Proof. Set $L_t^{\epsilon_k} = X_t^{\epsilon_k} - X_t$. Then

$$\begin{aligned} & e^{-\int_0^t (K_s + \rho(X_s)) ds} \|L_t^{\epsilon_k}\|_H^2 \\ = & \int_0^t e^{-\int_0^s (K_r + \rho(X_r)) dr} \left(- (K_s + \rho(X_s)) \|L_s^{\epsilon_k}\|_H^2 \right. \\ & \quad \left. + 2 \langle \mathcal{A}(s, X_s^{\epsilon_k}) - \mathcal{A}(s, X_s), L_s^{\epsilon_k} \rangle_{V^*, V} \right) ds \\ & + 2 \int_0^t e^{-\int_0^s (K_r + \rho(X_r)) dr} \left\langle \int_{\mathbb{X}} f(s, X_s^{\epsilon_k}, z) (\varphi_{\epsilon_k}(s, z) - 1) \nu(dz) \right. \\ & \quad \left. - \int_{\mathbb{X}} f(s, X_s, z) (\varphi(s, z) - 1) \nu(dz), L_s^{\epsilon_k} \right\rangle_{H, H} ds \\ & + 2\epsilon_k \int_0^t e^{-\int_0^s (K_r + \rho(X_r)) dr} \left\langle \int_{\mathbb{X}} f(s, X_s^{\epsilon_k}, z), L_s^{\epsilon_k} \right\rangle_{H, H} \tilde{N}^{\epsilon_k^{-1} \varphi_{\epsilon_k}}(dz, ds) \\ & + \epsilon_k^2 \int_0^t e^{-\int_0^s (K_r + \rho(X_r)) dr} \int_{\mathbb{X}} \|f(s, X_s^{\epsilon_k}, z)\|_H^2 N^{\epsilon_k^{-1} \varphi_{\epsilon_k}}(dz, ds) \\ = & I_1(t) + I_2(t) + I_3(t) + I_4(t). \end{aligned} \quad (5.29)$$

(H2) implies

$$I_1(t) \leq 0. \quad (5.30)$$

By (5.19) and (5.20), we have

$$\begin{aligned} & \mathbb{E} \left(\sup_{t \in [0, T]} \left| \int_0^t e^{-\int_0^s (K_r + \rho(X_r)) dr} \left\langle \int_{\mathbb{X}} f(s, X_s^{\epsilon_k}, z) (\varphi_{\epsilon_k}(s, z) - 1) \nu(dz), L_s^{\epsilon_k} \right\rangle_{H, H} ds \right| \right) \\ \leq & \mathbb{E} \left(\int_0^T \int_{\mathbb{X}} \|f(s, X_s^{\epsilon_k}, z)\|_H |\varphi_{\epsilon_k}(s, z) - 1| \|L_s^{\epsilon_k}\|_H \nu(dz) ds \right) \\ \leq & \mathbb{E} \left(\int_0^T \int_{\mathbb{X}} \|X_s^{\epsilon_k}\|_H L_f(s, z) |\varphi_{\epsilon_k}(s, z) - 1| \|L_s^{\epsilon_k}\|_H \nu(dz) ds \right) \rightarrow 0, \text{ as } \epsilon_k \rightarrow 0. \end{aligned} \quad (5.31)$$

Then it is not difficult to obtain

$$\lim_{\epsilon_k \rightarrow 0} \mathbb{E} \left(\sup_{t \in [0, T]} |I_2(t)| \right) = 0. \quad (5.32)$$

For I_3 ,

$$\begin{aligned}
& \mathbb{E} \left(\sup_{t \in [0, T]} |I_3(t)| \right) \\
& \leq \mathbb{E} \left(\int_0^T \int_{\mathbb{X}} 4\epsilon_k^2 \|L_s^{\epsilon_k}\|_H^2 \|f(s, X_s^{\epsilon_k}, z)\|_H^2 N^{\epsilon_k^{-1}\varphi_{\epsilon_k}}(ds, dz) \right)^{1/2} \\
& \leq 2\mathbb{E} \left(\sqrt{\epsilon_k} \sup_{s \in [0, T]} \|L_s^{\epsilon_k}\|_H \left(\int_0^T \int_{\mathbb{X}} \epsilon_k \|f(s, X_s^{\epsilon_k}, z)\|_H^2 N^{\epsilon_k^{-1}\varphi_{\epsilon_k}}(ds, dz) \right)^{1/2} \right) \\
& \leq 2\sqrt{\epsilon_k} \left(\mathbb{E} \left(\sup_{t \in [0, T]} \|L_t^{\epsilon_k}\|_H^2 \right) \right)^{1/2} \left(\mathbb{E} \left(\int_0^T \int_{\mathbb{X}} \|f(s, X_s^{\epsilon_k}, z)\|_H^2 \varphi_{\epsilon_k}(s, z) \nu(dz) ds \right) \right)^{1/2} \\
& \leq 2\sqrt{\epsilon_k} \left(\mathbb{E} \left(\sup_{t \in [0, T]} \|L_t^{\epsilon_k}\|_H^2 \right) \right)^{1/2} \\
& \quad \times \left(\mathbb{E} \left(1 + \sup_{t \in [0, T]} \|X_t^{\epsilon_k}\|_H^2 \right) \sup_{\varphi \in S^N} \int_0^T \int_{\mathbb{X}} L_f^2(s, z) \varphi(s, z) \nu(dz) ds \right)^{1/2} \\
& \rightarrow 0, \text{ as } \epsilon_k \rightarrow 0. \tag{5.33}
\end{aligned}$$

For I_4 ,

$$\begin{aligned}
& \mathbb{E} \left(\sup_{t \in [0, T]} |I_4(t)| \right) \\
& \leq \epsilon_k \mathbb{E} \left(\int_0^T \int_{\mathbb{X}} \|f(s, X_s^{\epsilon_k}, z)\|_H^2 \varphi_{\epsilon_k}(s, z) \nu(dz) ds \right) \\
& \leq \epsilon_k \mathbb{E} \left(1 + \sup_{t \in [0, T]} \|X_t^{\epsilon_k}\|_H^2 \right) \sup_{\varphi \in S^N} \int_0^T \int_{\mathbb{X}} L_f^2(s, z) \varphi(s, z) \nu(dz) ds \\
& \rightarrow 0, \text{ as } \epsilon_k \rightarrow 0. \tag{5.34}
\end{aligned}$$

Combining (5.29)–(5.34), we have

$$\lim_{\epsilon_k \rightarrow 0} \mathbb{E} \left(\sup_{t \in [0, T]} \left(e^{-\int_0^t (K_s + \rho(X_s)) ds} \|L_t^{\epsilon_k}\|_H^2 \right) \right) = 0.$$

Then

$$\lim_{\epsilon_k \rightarrow 0} \mathbb{E} \left(e^{-\int_0^T (K_s + \rho(X_s)) ds} \left(\sup_{t \in [0, T]} \|L_t^{\epsilon_k}\|_H^2 \right) \right) = 0.$$

This implies that there exists a subsequence ϖ_k such that X^{ϖ_k} converges to X $\bar{\mathbb{P}}$ -a.s. \square

6. Verification of Condition 2.1

Recall (4.5) and (3.1), we have

Theorem 6.1. *Fixed $N \in \mathbb{N}$, and let $\varphi_\epsilon, \varphi \in \tilde{\mathbb{A}}^N$ be such that φ_ϵ converges in distribution to φ as $\epsilon \rightarrow 0$. Then*

$$\mathcal{G}^\epsilon(\epsilon N^{\epsilon^{-1}\varphi_\epsilon}) \Rightarrow \mathcal{G}^0(\nu_T^\varphi).$$

Proof. Recall $\bar{\mathbb{M}}$ in Section 2 and notations in Proposition 4.1. Denote

$$\Pi = \left(S^N, D([0, T], V^*), C([0, T], V^*), C([0, T], V^*), \bar{\mathbb{M}} \right).$$

Proposition 4.1 implies that the laws of $\left\{ \left(\varphi_\epsilon, M^\epsilon, Z^\epsilon, Y^\epsilon, \bar{N} \right), \epsilon > 0 \right\}$ is tight in Π . Let $\left(\varphi, 0, Z, Y, \bar{N} \right)$ be any limit point of the tight family. By the Skorohod's embedding theorem, taking a version on a new probability space if necessary, we may and will assume that

$$\left(\varphi_\epsilon, M^\epsilon, Z^\epsilon, Y^\epsilon, \bar{N} \right) \longrightarrow \left(\varphi, 0, Z, Y, \bar{N} \right) \text{ in } \Pi, \bar{\mathbb{P}}\text{-a.s.}$$

Set $\tilde{X}^\epsilon = x + M^\epsilon + Z^\epsilon + Y^\epsilon$ and $X = x + Z + Y$. From the equation satisfied by the original processes, we may and will assume that \tilde{X} still satisfy equation (4.4).

Using the fact that if $f_n \in D([0, T], \mathbb{R})$ and $\lim_{n \rightarrow \infty} f_n = 0$ with the Skorohod topology of $D([0, T], \mathbb{R})$, then $\lim_{n \rightarrow \infty} \sup_{t \in [0, T]} |f_n(t)| = 0$. We have

$$\lim_{\epsilon \rightarrow 0} \sup_{t \in [0, T]} \|M^\epsilon(t)\|_{V^*} = 0, \quad \bar{\mathbb{P}}\text{-a.s.}$$

Notice that

$$\lim_{\epsilon \rightarrow 0} \sup_{t \in [0, T]} \|Z^\epsilon(t) - Z(t)\|_{V^*} = 0, \quad \bar{\mathbb{P}}\text{-a.s.}$$

and

$$\lim_{\epsilon \rightarrow 0} \sup_{t \in [0, T]} \|Y^\epsilon(t) - Y(t)\|_{V^*} = 0, \quad \bar{\mathbb{P}}\text{-a.s.},$$

we have

$$\lim_{\epsilon \rightarrow 0} \sup_{t \in [0, T]} \|\tilde{X}^\epsilon(t) - X(t)\|_{V^*} = 0, \quad \bar{\mathbb{P}}\text{-a.s.}$$

Finally, following the proof of Proposition 5.1 and Lemma 5.5, we can obtain X is the unique solution of (5.27), and there exists a subsequence ϖ_k that

$$\lim_{\varpi_k \rightarrow 0} \sup_{t \in [0, T]} \|\tilde{X}^{\varpi_k}(t) - X(t)\|_H = 0, \quad \bar{\mathbb{P}}\text{-a.s.}$$

which implies this theorem. □

We have finished to verify the second part of Condition 2.1. To obtain the first part of Condition 2.1, we just need to replace $\epsilon \int_{\mathbb{X}} f(t, \tilde{X}_{t-}^\epsilon, z) \tilde{N}^{\epsilon^{-1}\varphi_\epsilon}(dz, dt)$ by 0 in (4.4) and replacing φ_ϵ by deterministic elements g_n in the proof of Lemma 4.4–Lemma 5.1, then we can similarly prove the following result.

Theorem 6.2. Recall \mathcal{G}^0 in (3.1). For all $N \in \mathbb{N}$, let $g_n \rightarrow g$ as $n \rightarrow \infty$. Then

$$\lim_{n \rightarrow \infty} \sup_{t \in [0, T]} \|\mathcal{G}^0(\nu_T^{g_n})(t) - \mathcal{G}^0(\nu_T^g)(t)\|_H = 0.$$

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