

BAYESIAN ANOMALY DETECTION METHODS FOR SOCIAL NETWORKS

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Learning the network structure of a large graph is computationally demanding, and dynamically monitoring the network over time for any changes in structure threatens to be more challenging still.

This paper presents a two-stage method for anomaly detection in dynamic graphs: the first stage uses simple, conjugate Bayesian models for discrete time counting processes to track the pairwise links of all nodes in the graph to assess normality of behavior; the second stage applies standard network inference tools on a greatly reduced subset of potentially anomalous nodes. The utility of the method is demonstrated on simulated and real data sets.

1. Introduction. Anomaly detection on graphs of social or communication networks has important security applications. The definition of a graph anomaly typically depends on the data and application of interest. Typically anomaly detection focuses on the connections amongst the graph's entities and various methods have been developed for their analysis. Examples include spectral decompositions (an area excellently summarized in [von Luxburg, 2007](#)), scan statistics ([Priebe et al., 2005](#)) and random walks ([Pan et al., 2004](#); [Tong et al., 2006](#)). These methods are generally computationally demanding when applied to very large networks; also, in deciding upon which one to use, an explicit choice is being made on the type of anomaly sought. The interest of this paper is anomaly detection in large dynamic networks, in a context where in principle any type of anomaly should be detected. We focus on problems relating to anomalies in social networks, and present analyses of real and simulated data from this area. In each case, the network is observed over a sequence of discrete times, where each observation provides only a partial view of the full connectivity; a complete view of the network is provided by the time series as a whole.

The real data come from the European Commission Joint Research Centre's (JRC) European Media Monitor (EMM) (<http://emm.jrc.it>). EMM

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is a web intelligence service, providing real-time press and media summaries to Commission cabinets and services, including a breaking news and alerting service. This service requires JRC to parse each of the news documents to extract the relevant information and tag the story as belonging to a particular topic. For our analysis, JRC provided 131 weeks of Media Monitor data sourced from a collection of approved websites, starting from 1st January 2005, although this period includes a known two-week server downtime at the end of the first month. The data were extracted from news articles tagged as being related to terrorist attacks, political unrest and security. The data we receive are undirected and in a simple list format showing the date of a reported link and the names of the two individuals involved.

The simulated data come from the VAST Challenge 2008 (<http://www.cs.umd.edu/hcil/VASTchallenge08>); we consider the simulated cell phone data from the Mini Challenge focused in the area of social network analysis. The cell phone call records cover a fictional ten-day period on an island, narrowed to 400 unique cell phones during this period. As well as the time of each phone call and details of who phoned whom, an identifier of the cell tower from which the call originated is also given. The records should provide critical information about an important social network structure. From the results of award winning published work on this challenge (Ye et al., 2008), work which used a combination of *PageRank* (Brin and Page, 1998) and visual analytic methods, there is good reason to suspect that the major anomalous activity occurs on the eighth day and involves a list of at least eleven individuals.

2. Two-stage approach. The idea behind the method presented here is a simple one: If a social network has fundamentally changed in some important way, then in most contexts this is likely to suggest that there are some individuals who are now either communicating more or less *frequently* than usual, or communicating with *different* individuals than usual. Beyond this view there may well be much more subtle network structure to examine, but initially taking this more simple view allows good targets to be quickly identified, with the important possibility to then zoom-in and investigate such local structure.

In this paper we present a two-stage approach to dynamic anomaly detection. The first stage is a sweep of the database to identify potentially anomalous nodes in the network; in the second stage, a subgraph is constructed around this set of nodes, usually extended to include other nodes which have recently (or perhaps ever) communicated with a node in this set, and then standard network analytic tools are used to investigate structure

in this vastly reduced subnetwork.

Technically, for each pair of individuals we independently model the communications between them over time as a counting process, with the increments of the process following a Bayesian probability model. At any point in time, we test whether their relationship has changed to a degree that is statistically significant. If the derived predictive p-value falls below a fixed threshold, this represents a departure from previously modeled behavior. The node pair are then said to be anomalous and are added to the set of anomalous nodes for this period. Such an approach is statistically principled and computationally very simple. By assuming independence of the processes the method is also fully parallelizable, in the sense that each node pair is examined in isolation. This assumption of independence will be approximately acceptable only in some circumstances, and a method which seeks to relax this assumption is considered in Section 3.4.

Once a reduced subset of interesting nodes has been identified, standard network tools such as spectral clustering can be much more readily deployed; also, at this stage we are now interested in the simpler problem of characterizing structure, such as identifying clusters, rather than looking for changes in this structure, the latter being a task which requires additional metrics to be specified.

The threshold at which p-values are judged to be significant must be set by the user. In this paper we use a 0.05 threshold, but smaller or larger critical values would lead to correspondingly smaller or larger networks of potentially anomalous nodes. In practice a good threshold can be chosen to be as large as possible subject to the resulting anomaly network being of a manageable size such that follow-up investigation is feasible.

3. Discrete time counting process models. The number of communications over time are treated as simple Bayesian discrete time counting processes with conditionally independent increments. For each period in time, the number of communications between individuals will represent the current weight of their association in the network.

We first consider some different ways of counting up the communications. Then, simple Bayesian probability models are given for learning about such counting processes. Full details of these probability models and the parameterizations used are given in [Supplement A](#).

3.1. Pairwise, individual and total activity analysis. For each pair of individuals (i, j) , starting from time 0 when the data collection process begins let $N_{ij}(t)$ be the number of communications made from i to j up until discrete time t ; alternatively, for a simpler binary view of the network, let $N_{ij}(t)$

be the number of periods in which i has communicated with j by time t . If the graph is undirected we have the simplification $N_{ij}(t) \equiv N_{ji}(t)$.

Let P_{ij} be a probability model for the increments $dN_{ij}(t) = N_{ij}(t) - N_{ij}(t-1)$ under normal circumstances. In the simplest setting, we can consider $dN_{ij}(1), dN_{ij}(2), \dots$ as independent realisations from P_{ij} ; the distribution P_{ij} corresponds to the normal mode of communication behavior for this pair of individuals. Anomalous behavior at time t , on the other hand, can be regarded as a value of $dN_{ij}(t)$ drawn from a distribution other than P_{ij} . The aim is then to detect which values of $dN_{ij}(t)$ are not draws from the unknown P_{ij} .

For a realized value of $dN_{ij}(t) = n$, we find a two-sided Bayesian p-value as the posterior probability of observing a count as extreme as n ; this posterior distribution is a marginal calculation based on our revised beliefs about the unknown distribution P_{ij} in light of all other periods of data we have observed. Carefully chosen conjugate Bayesian models allow for this inferential process to be analytically tractable (see [Bernardo and Smith, 1994](#), for details). For example, a (simplistic) parametric choice for P_{ij} could be $\text{Poisson}(\lambda_{ij})$ for unknown rate parameter $\lambda_{ij} > 0$. Completing the model specification with a gamma prior for λ_{ij} ensures the posterior predictive distribution for a future period is calculable as a simple ratio of Poisson-gamma mass functions. Where no obvious parametric form for P_{ij} exists, nonparametric Bayesian inference is available via the Dirichlet Process ([Ferguson, 1973](#)).

In the absence of specific prior information about any of the nodes, identical prior distributions are adopted for each of the node pair counting processes $N_{ij}(t)$. So in the first observation period, each node pair has the same probability of being active and hence the implied model on the whole network belongs to the well-known class of exponential random graph models (ERGMs) ([Wasserman and Pattison, 1996](#)). From the second time period onwards, however, the posterior predictive distributions will differ between node pairs according to the activity which has been observed and so here we see a departure from ERGMs.

The framework above can be regarded as an independent, *pairwise* analysis of the members of the network. If $dN_{ij}(t)$ is the *adjacency* of node i to node j at time t , then a similar *individual*-based analysis considers the

outdegree and *indegree* of node i , given by the respective increments of

$$(3.1) \quad N_{i\cdot}(t) = \sum_{j \neq i} N_{ij}(t),$$

$$(3.2) \quad N_{\cdot i}(t) = \sum_{j \neq i} N_{ji}(t).$$

These two summed processes correspond to the number of outgoing (Equation (3.1)) and incoming (Equation (3.2)) communications over time for individual i . For an undirected graph the indegree and outdegree are equivalent and Equation (3.2) is redundant. Again, we can assume exchangeable increments following similar probability models for these processes and look for outlying values in each time period.

Finally, as a highest level summary we can monitor the *degree sum* of the network over time, given by the increments of

$$N_{\cdot\cdot}(t) = \sum_i \sum_{j > i} N_{ij}(t) \quad \text{or} \quad N_{\cdot\cdot}(t) = \sum_i \sum_{j \neq i} N_{ij}(t),$$

where the two definitions correspond to undirected and directed graphs respectively. Such processes monitor the overall network activity level. Again, the same conjugate Bayesian probability models can be applied at this level.

3.2. Parametric inference and hurdle models. Social network graphs are typically sparse (Faloutsos et al., 2004). Particularly in larger networks, most pairs of individuals will not communicate with one another, suggesting a vanishing fraction of node pairs actually have an edge between them. This sparsity can be seen as providing an analytical advantage here, as there will be fewer non-trivial node pair relationships in the graph.

However, when the network is viewed temporally, the sparsity of the network is further increased. As we will see in the examples later, even individuals who are related will spend much of the time not communicating. This type of sparsity is problematic when modelling the counting processes, as the large number of time periods showing zero communications mean that standard exponential family distributions are inappropriate for modelling normal behavior.

We extend the exponential family probability models to their *hurdle* variants (Mullahy, 1986), which incorporate additional probability variables for determining whether or not the node pair are active in a given period t . The modelling of the process $dN_{ij}(t)$ is split into two parts, firstly a hurdle process for determining whether $dN_{ij}(t) = 0$ or $dN_{ij}(t) > 0$, and then

secondly another stochastic process governing the value taken by $dN_{ij}(t)$ at those times when the hurdle process dictates that $dN_{ij}(t) > 0$.

At time t let $A_{ij}(t)$ be the number of time periods $u \leq t$ in which $dN_{ij}(u) > 0$, meaning the node pair (i, j) were active. The increment for time t , $dA_{ij}(t) = A_{ij}(t) - A_{ij}(t-1)$ takes value 0 or 1, with $dA_{ij}(t) = 1$ indicating the pair were active in time period t . A counting process model with Bernoulli increments specifies $A_{ij}(t)$.

For times when the two individuals are active, the hurdle model also requires a second model for the increments $dN_{ij}(t) \geq 1$. We use the shifted quantities $dN_{ij}(t) - 1 \geq 0$ to define the increments of a second counting process $dB_{ij}(s)$ by the equations

$$\begin{aligned} dB_{ij}(s) &= dN_{ij}(t_s) - 1, \quad s = 1, 2, 3, \dots, \\ t_s &= \min\{t : A_{ij}(t) = s\}, \end{aligned}$$

with resulting counting process $B_{ij}(s) = \sum_{u=1}^s dB_{ij}(u)$.

For the hurdle model we therefore need to specify two (typically independent) models for the counting processes $B_{ij}(\cdot)$ and $A_{ij}(\cdot)$. Assuming independence of $A_{ij}(\cdot)$ and $B_{ij}(\cdot)$, the increments of the compensator $\Lambda_{ij}(\cdot)$ for the process $N_{ij}(\cdot)$ can be expressed as

$$d\Lambda_{ij}(t) = \mathbb{E}[dN_{ij}(t)|\mathcal{H}_{t-1}] = \mathbb{E}[dA_{ij}(t)|\mathcal{H}_{t-1}](\mathbb{E}[dB_{ij}(t)|\mathcal{H}_{t-1}] + 1),$$

where for $N(t) = \{N_{ij}(t) : i \neq j\}$, $\mathcal{H}_t = \{N(u) | u = 0, 1, 2, \dots, t\}$ is the history of the processes up until time t . Then, since

$$\begin{aligned} \mathbb{E}[dN_{ij}^2(t)|\mathcal{H}_{t-1}] &= \mathbb{E}[dA_{ij}(t)|\mathcal{H}_{t-1}](\mathbb{E}[(dB_{ij}(t) + 1)^2|\mathcal{H}_{t-1}]) \\ &= \mathbb{E}[dA_{ij}(t)|\mathcal{H}_{t-1}]\{\text{Var}[dB_{ij}(t)|\mathcal{H}_{t-1}] + 1\} \\ &\quad + d\Lambda_{ij}(t)\mathbb{E}[dB_{ij}(t)|\mathcal{H}_{t-1}], \end{aligned}$$

it follows that the increments of the predictable variation of the counting process martingale $M_{ij}(t) = N_{ij}(t) - \Lambda_{ij}(t)$ satisfy

$$\begin{aligned} d\langle M_{ij}(t) \rangle &= \mathbb{E}[dA_{ij}(t)|\mathcal{H}_{t-1}]\{\text{Var}[dB_{ij}(t)|\mathcal{H}_{t-1}] + 1\} \\ &\quad + d\Lambda_{ij}(t)\mathbb{E}[dB_{ij}(t)|\mathcal{H}_{t-1}] - d\Lambda_{ij}^2(t). \end{aligned}$$

These equations can be used for checking how well the models for $N_{ij}(t)$ compare in fitting the data.

3.2.1. Bernoulli process. The hurdle process increments $\{dA_{ij}(t)\}$ are most simply treated as a Bernoulli process

$$dA_{ij}(t) \sim \text{Bernoulli}(\pi_{ij}), \quad t = 1, 2, 3, \dots,$$

